

Minimum Spanning Tree (MST)

Input: (undirected connected) $G = (V, E, c)$

c_e is the cost of the edge e ,

$c_e > 0$ and w.l.o.g all c_e 's are distinct.

Output: a subset $T \subseteq E$ so that $G = \langle V, T \rangle$ is connected and the total cost $\sum_{e \in T} c_e$ is minimized.

Claim (4.16): T is a tree.

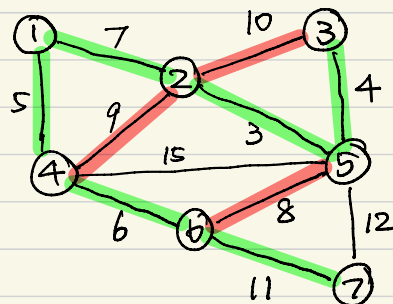
Proof: suppose T contains a cycle C ,
then if we any edge $e \in C$, the graph $(V, T - \{e\})$ is still connected.



Kruskal's algorithm:

1. Start with $T = \emptyset$.
2. Sort edges in E by cost in ascending order.
3. Iterate over all edges, add e to T as long as it does not create a cycle.

Example:



Legend:
Green line: $\in T$
Red line: $\notin T$

Output:

$T =$ all green edges

$$\text{cost}(T) = 3 + 4 + 5 + 6 + 7 + 11 \\ = 36.$$

Correctness:

Theorem (4.18): Kruskal's algorithm produces an MST.
(page 146)

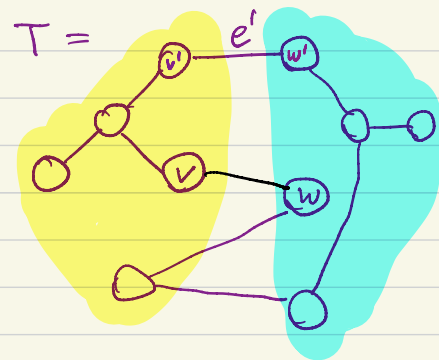
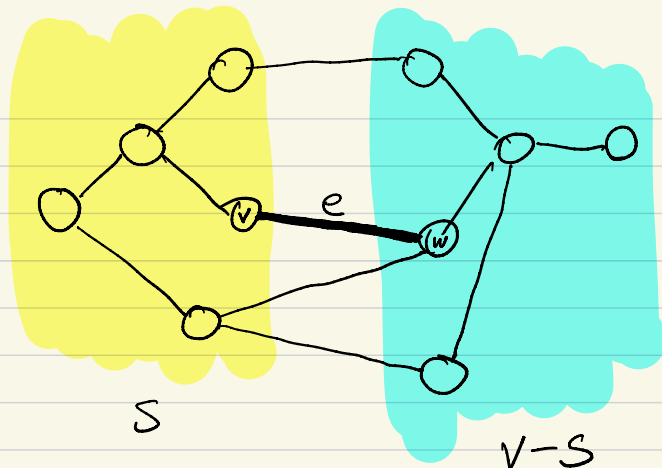
Lemma (4.17): Assume c_e 's are distinct.

Fix $S \subseteq V$.

Let e be the minimum cost edge with
one end in S and one end in $V - S$.

Then e must appear in every MST.

Proof.



Suppose $e = (v, w)$ is the cheapest edge between S and $V-S$.
Suppose there is an MST T s.t. $e \notin T$.

Because T is a spanning tree, there is a path P from v to w in T .
Since $v \in S$ and $w \notin S$, P must leave S at some point.

Let e' be the first edge in P that leaves S .
 (v', w')

$T + \{e\} - \{e'\}$ is a spanning tree with smaller cost.

- the cost is smaller because $c_e < c_{e'}$.
- $T + \{e\}$ contains a unique cycle C and moreover $e' \in C$.

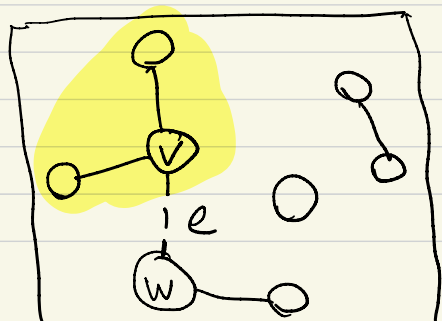
$\Rightarrow T + \{e\} - \{e'\}$ is connected.

" $T + \{e\} - \{e'\}$ " has $(n-1)$ edges.

Proof (correctness of Kruskal):

Consider an edge $e = (v, w)$ added by Kruskal's algorithm.

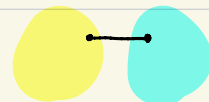
Let S be v 's connected component just before adding e .



- $w \notin S$ (o.w. adding e creates a cycle).
- no edge from S to $V-S$ has been considered (any such edge would have been added).

Thus, e must be the cheapest edge that leaves S .
so it is safe to include e .

Moreover, Kruskal's output must be connected.



Prim's algorithm.

1. Pick a root $s \in V$.
2. $S = \{s\}$. (All nodes in S are connected.)
3. Repeat the following until $S = V$:

Add v to S where $v \notin S$ minimizes the "attachment cost".

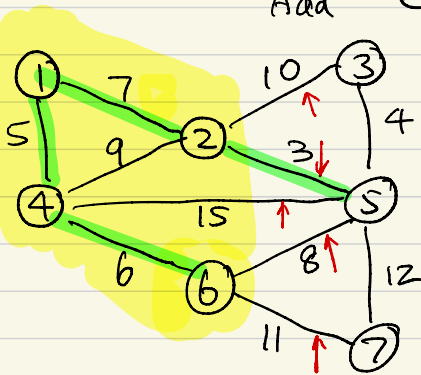
$$\min_{e=(u,v), u \in S} C_e.$$

(breaking ties arbitrarily)

Add $e=(u,v)$ to T .

4. Return T .

Example:



Correctness:

- Every time the algorithm adds an edge e , e is the cheapest edge between S and $V-S$.
- T is a spanning tree at the end.

Runtime of Prim: $O(m \log n)$.

Similar to Dijkstra's algorithm.

We will use a min-heap H .

Overall. $\begin{cases} O(n) & H.\min() \\ O(m) & H.\text{changekey}() \end{cases}$ each call takes $O(1)$ time
each call takes $O(\log n)$ time

$$\text{Overall runtime} = O(n \cdot 1 + m \cdot \log n) = O(m \log n).$$

Runtime of Kruskal:

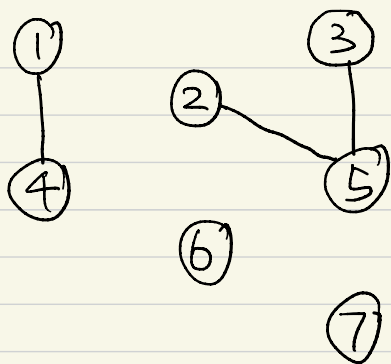
1. Sort all edges: $O(m \log m) = O(m \log n)$ ($m \leq n^2$)
2. Check (in total $O(m)$ times) whether adding e would cause a cycle. **How?** ($O(n)$ via DFS)

Can we do it faster?

The Union-Find data structure. (page 152)

- $\text{Init}()$: all elements are in separate sets.
- $\text{Union}(x, y)$: merge the set containing x with the set containing y .
- $\text{Find}(x)$: return the "name" of the set that x is in.

We use this data structure to maintain the set of connected components (which are changing over time) in Kruskal's algorithm.



$\{1, 4\}$ $\{2, 3, 5\}$ $\{6\}$ $\{7\}$. representative element

When we consider any edge $e = (u, v)$
 If $(\text{find}(u) \neq \text{find}(v))$ then
 Add e to T
 Union(u, v).
 End if.

Union-Find First Attempt.

arrays $\rightarrow$ $\text{name}[i]$: name of the set that contains i .
 $\text{size}[j]$: size of the set with name j .
 functions $\rightarrow$ $\text{Init}()$: $\text{name}[i] = i$, $\text{size}[i] = 1$;
 $\text{Find}(x)$: return $\text{name}[x]$;
 $\text{Union}(x, y)$:

$x = \text{name}[x]$;
 $y = \text{name}[y]$;
 If $(\text{size}[x] < \text{size}[y])$ swap(x, y);
 (so w.l.o.g $\text{size}[x] \geq \text{size}[y]$)
 For every element i in set " y ":
 $\text{name}[i] = x$;
 End For
 $\text{size}[x] = \text{size}[x] + \text{size}[y]$;

Example: Before

	1	2	3	4	5	6	7	(index)
name :	1	2	2	1	2	6	7	
size :	2	3				1	1	

Union(4, 5)

$x = 4, y = 5 \Rightarrow x = 1, y = 2$.

$\Downarrow$
 $x = 2, y = 1$ (swapped so that $\text{size}[x] \geq \text{size}[y]$)

For $i \in \{1, 4\}$.

$\text{name}[i] = 2$

End for

$\text{size}[2] = \text{size}[2] + \text{size}[1]$.

After.

	1	2	3	4	5	6	7	(index)
name	2	2	2	2	2	6	7	
size		5				1	1	

We always merge the smaller set into the bigger one!

Runtime: Init: $O(n) \times O(1)$ Find: $O(1) \times O(m)$

Claim: The first K union operations run in total time $O(K \log K)$. $k=n$

$\Rightarrow$ Kruskal runs in time: $O(\text{Sorting} + m + \text{find} + \text{union}) = O(m \log n)$

Proof sketch:

After $k > 1$ union operations, the largest set has size $O(k)$.

How many times can $\text{name}[i]$ change?

Once per $\text{union}(A, B)$ if $i \in B$ and $|B| \leq |A|$.

At most $O(\log k)$ times because the size of the set $\text{name}[i]$ at least doubles each time.

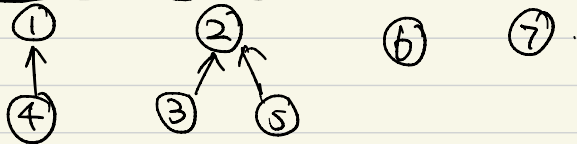
At most $2k$ $\text{name}[i]$ are changed.

$$\Downarrow \\ O(k \log k).$$

Not very ideal because sometimes $\text{Union}(x, y)$ can take $\Omega(n)$ time.

Example: $\text{name} = \underbrace{11 \dots 11}_{n/2} \quad \underbrace{22 \dots 2}_{n/2}$

Union-Find Second Attempt



index	1	2	3	4	5	6	7	(-1 if no parent)
parent	-1	-1	2	1	2	-1	-1	

$\text{Init}()$: $\text{parent}[i] = -1 \quad \forall i$.

$\text{Find}(x)$: return the root of x .

$\text{Find}(x)$:

while $(\text{parent}[x] \neq -1)$

$x = \text{parent}[x]$

end while

return x

$\text{Union}(x, y)$: $x = \text{Find}(x)$, $y = \text{Find}(y)$.

merge the smaller set into the bigger one.

If $\text{size}[x] \geq \text{size}[y]$

$\text{parent}[y] = x$:

$\text{size}[x] = \text{size}[x] + \text{size}[y]$

Else

$\text{parent}[x] = y$.

$\text{size} \dots$

Example: $\text{Union}(4, 5)$.



Runtime:

$\text{Init}()$: $O(n)$

$\text{Find}()$: $O(\log n)$

the depth of any tree is at most $O(\log n)$

$\text{Union}()$: $O(1)$

after $x = \text{find}(x)$ and $y = \text{find}(y)$.

Runtime of

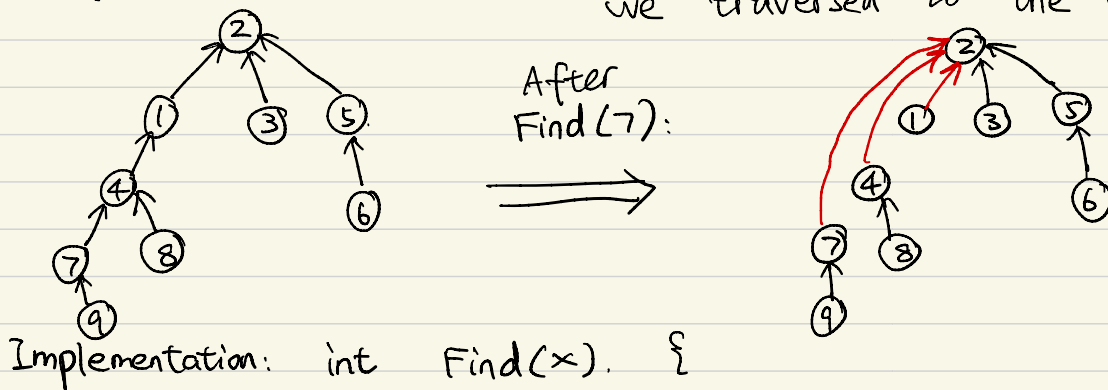
Kruskal under this Union-Find implementation = $O(m \log n + m \log n + n)$

sorting find union

Union-find Third Attempt (the real version)

Building on the second attempt, we add one more optimization.

Path compression: After $\text{find}(x)$, point all the elements we traversed to the root.



Implementation:

```
int Find(x). {
    If (x == parent[x]) return x;
    root = Find(parent[x]); ← recursion,
    parent[x] = root;
    return root;
}
```

$\text{find}(7) \rightarrow \text{find}(4) \rightarrow \text{find}(1) \rightarrow \text{find}(2) = 2$

$\text{parent}[7] = 2 \leftarrow \text{parent}[4] = 2 \leftarrow \text{parent}[1] = 2$

Upshot: Next time we call $\text{find}(7)$ before any union operation takes $O(1)$ time.

Runtime: First K Union/Find operations

[Hopcroft and Ullman '73]

A "simple" proof (available on Union-Find Wikipedia page) ↓
shows that these K operations runs in $O(K \cdot \log^* n)$.

$\log^* n$: iterated logarithm.: # of times $\log$ needs to be applied for n to become 1.

$$\log_2^* (2^{2^{2^2}}) = 5$$

10¹⁹⁷²⁸

$O(m \cdot \alpha(n))$ [Tarjan '75]

$\Theta(m \cdot \alpha(n))$ [Fredman^{and} Saks '89]

↑
inverse Ackermann function (grows even slower than $\log^* n$).