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brainstorm ideas



09: Clocks and Timers/Counters



Today

Where we've been:

I/O Peripherals, interrupts, embedded architecture

Where we're going:

Time - clocks, timers, watchdogs

Brief introduction to scheduling (execution time, concurrency)



Keeping track of time: system clocks

Or “oscillators”

Basis of control of a CPU - instructions happen on “edges” of a clock (**why?**)

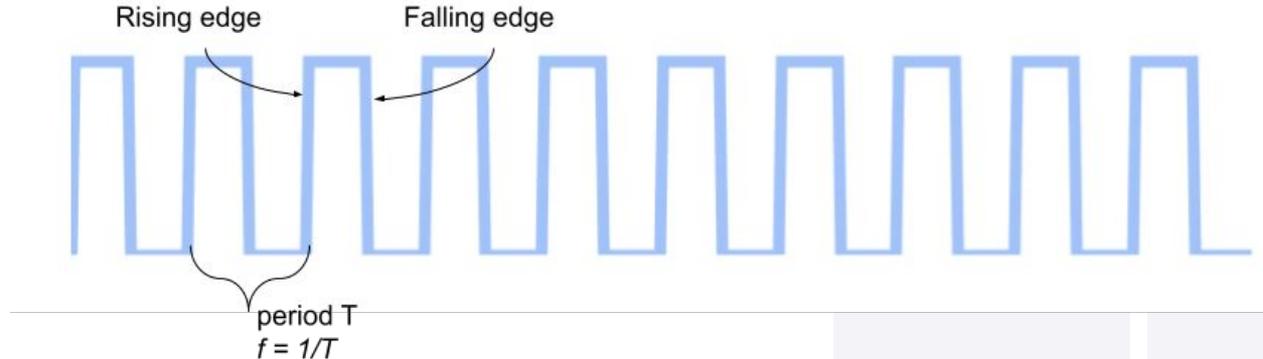
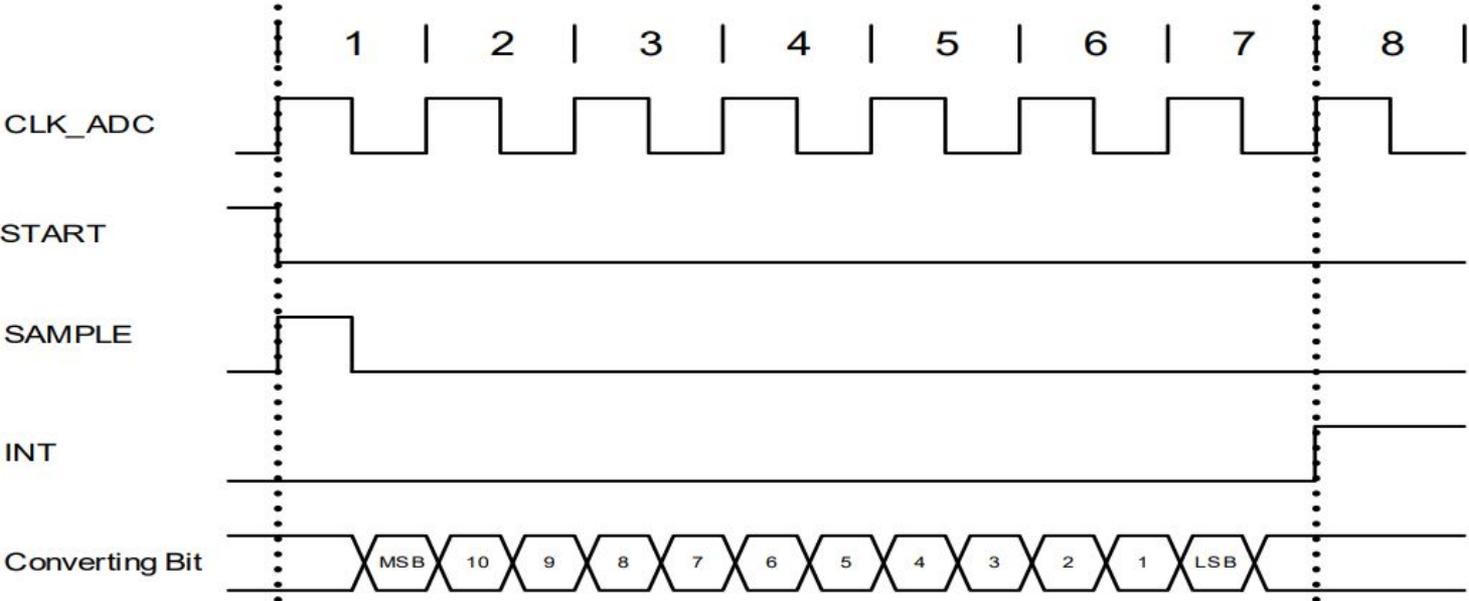


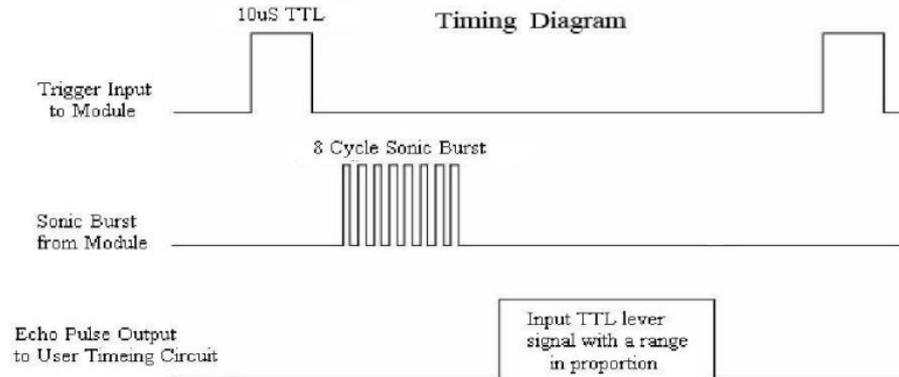
Figure 33-3. ADC Timing for One Conversion in Differential Mode without Gain



Timing Diagrams

Timing diagram

The Timing diagram is shown below. You only need to supply a short 10uS pulse to the trigger input to start the ranging, and then the module will send out an 8 cycle burst of ultrasound at 40 kHz and raise its echo. The Echo is a distance object that is pulse width and the range in proportion. You can calculate the range through the time interval between sending trigger signal and receiving echo signal. Formula: $\mu\text{s} / 58 = \text{centimeters}$ or $\mu\text{s} / 148 = \text{inch}$; or: the range = high level time * velocity (340M/S) / 2; we suggest to use over 60ms measurement cycle, in order to prevent trigger signal to the echo signal.



[Ultrasonic Proximity Sensor](#)

Counting time

Most basic way to keep track of time on a CPU: # of clock ticks

On an 8MHz CPU: 8 million clock ticks = 1 second

What is the largest unit of time we can keep track of in 32 bits on an 8MHz clock?

$$\frac{2^{32} \text{ ticks}}{8 \times 10^6 \frac{\text{ticks}}{\text{s}}}$$



*How do we keep track of
longer time periods?*



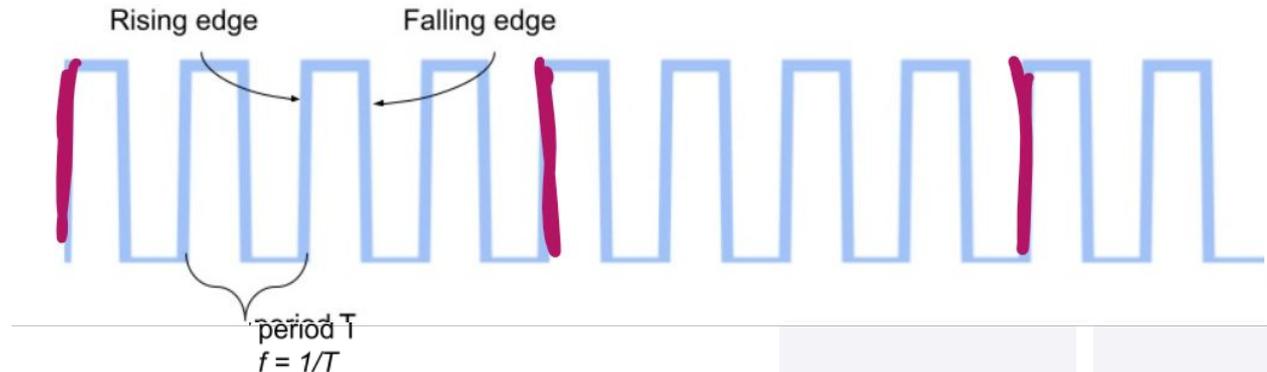
Timers

Keep track of time by incrementing every n clock ticks

On MCUs: hardware support

Often called something like TC (timer/counter) peripheral

Prescale the clock (divide it by 2, 4, 8...) and increment on the clock ticks





Uses for timers

- ◆ Count to a specific number of clock ticks and generate an interrupt (you will do this in lab!)
 - ◇ How Arduino keeps track of time for millis()
- ◆ Check for rollover and use this as a low-overhead way to measure time
 - ◇ Rollover: tick count reaches max value
 - ◇ Detected using polling or interrupt



Timer rollover math

48 MHz clock

Count every rising edge

32 bits: when will rollover happen?

*every $2^{32} / (4 * 10^6)$ s*



Keeping track of time without using floating point

Keep track of fractional seconds (say every 2^{-16} seconds)

- ◆ Precompute how many fractional seconds between each rollover
- ◆ Increment by that many fractional seconds in a variable



Quantization margins

With perfect timekeeping, # of fractional seconds expected in a day:

5,662,310,400

48 MHz clock, pre-scaled by 16, 8 bit counter

Effective frequency: 3 MHz

Rollover every ~ 0.0000853 ($2^8 / (3 * 10^6)$) seconds

= every ~ 5.59 fractional seconds (~ 6)

Rollovers in a day: 1,012,500,000

Fractional seconds counted: 6,075,000,000

Error: 7.3%



Clock drift

Imagine 32.768 kHz clock (common oscillator frequency - the SAM D21 has them too!)

0.001% drift rate (0.00001 seconds/second)

Drift during a day: 0.864 s

Drift during a year: 315.56 s



*When would you want to use
a slower clock? A faster
clock?*

*An 8-bit, 16-bit, or 32-bit
counter?*



Summary

MCU architecture provides:

- ◆ Clocks of different frequencies
- ◆ Pre-scaler constants for timers/counters
- ◆ Registers to count clock ticks
- ◆ Ability to detect timer/counter events such as rollover

**calculate elapsed
time based on these
configurations**