

#### Labs start this week!

- Today (Monday) or tomorrow
- Please bring your kit if you have it already
- If you want, install the Arduino IDE on your computer (and the SAMD drivers – step 1 of lab)

#### **Homeworks**

- Due before class Wednesday and Friday
- First one is out at the end of class
- Smaller, theoretical assignments
  - Typically a short reading and 1-3 questions
- Graded on good-effort completion
  - A preview of material taught in lecture
  - You're not expected to know it perfectly
  - If you get stuck, write down why you're stuck and move on



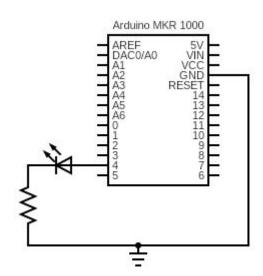
- Circuits are loops through which electricity flows (have a power source and some conductors)
- We learned computations for voltage, current, and power

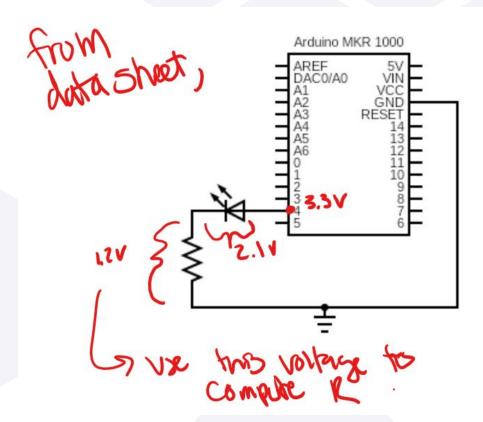


# Interpreting device data sheets

Yellow LED data sheet

### What is the actual minimum resistance?





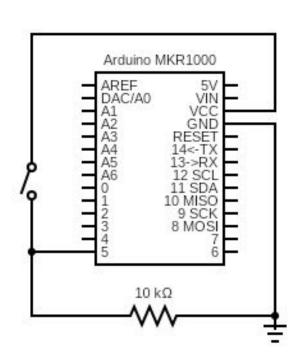
# **Digital devices**

Leds are digital **output** devices

Things like push buttons are digital **input** devices

(When connected correctly) are driven by or produce a high/low signal

# Circuit principle: must be closed for electricity to flow

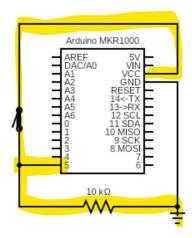


Pin 5 is configured as an input pin (receives electrical signal)

#### Button not pressed

# Arduino MKR1000 AREF 5V DAC/A0 VIN A1 VCC A2 GND A3 RESET A4 14<-TX A5 13->RX A6 12 SCL 0 11 SDA 11 SDA 11 SDA 11 SDA 12 SCK 3 8 MOSI 4 7 5 6 6

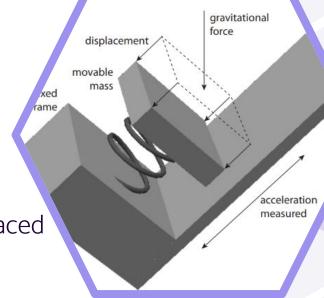
#### Button pressed





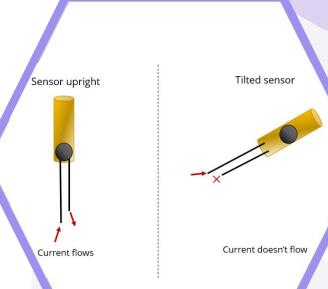
#### Your book talks about:

- Accelerometers (measure acceleration of displaced mass)
- Anemometers (air flow for velocity)
- GPS (satellite for position)
- Gyroscopes (gimbals and modern)
- Microphones
- Engine controllers, thermometers, cameras, chemical sensors, etc



# Other input components in your kits

- Photoresistor resistance changes based on light
- Potentiometer produces voltage based on rotation of the dial
- Tilt sensor Metal bearing completes circuit



## **Output components**

#### Your book talks about:

- LEDs
- Motors (DC)

#### Your kits have:

- LCD screen (controlled digitally)
- Servo motor (controlled by lengths of high/low pulses)
- Piezo speaker (electricity displaces film to make sound)

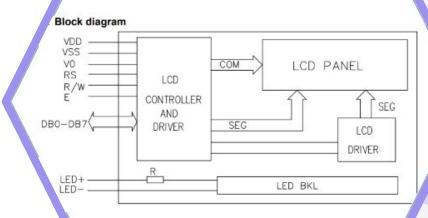


Image source



How do you control a DC motor that requires an external power source?

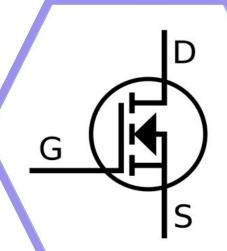


Basically an electric switch

Voltage applied to Gate connects Drain and Source

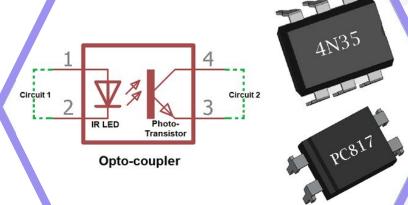
Come in different types (beyond the scope of this course)

The MOSFET transistor in your kits has a minimum gate voltage of 4.2V... what do we do?

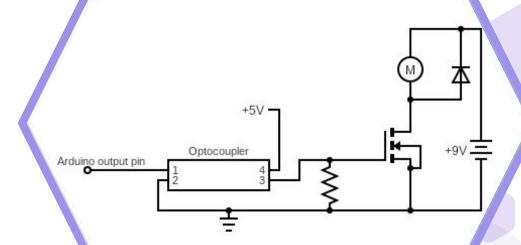


## **Optocouplers**

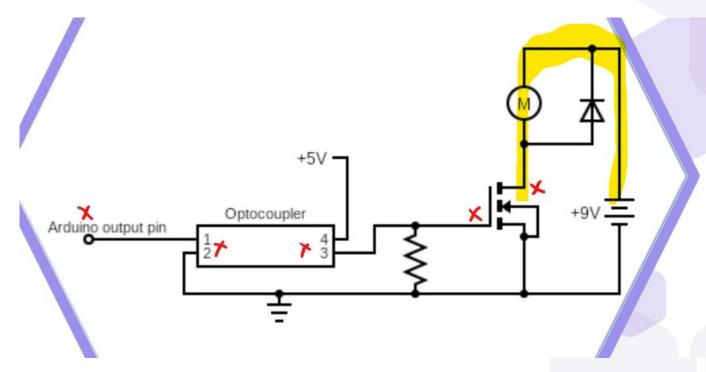
 Control one circuit using another, but they are completely electrically separate!



Motor driven using mosfet and optocoupler



# No voltage from Arduino output pin



# 3.3V from Arduino output pin

