

MARKOV CHAINS

- a) Modeling tool for sequences.
- b) Inference tool (as MCMC) - by using markov chains to defining a stochastic system.

MODELING TOOL:

Consider a sequence of random variables, $X_1, \dots, X_T$. The joint probability is:

$$P(X_1, \dots, X_T) = P(X_1) \cdot P(X_2 | X_1) \cdot P(X_3 | X_2, X_1) \dots$$

$$= P(X_1) \prod_{t=2}^T P(X_t | X_1, \dots, X_{t-1})$$

↓
of parameters grow with t .

Markovian Assumption:

First order: $P(X_1, \dots, X_T) = P(X_1) P(X_2 | X_1) P(X_3 | X_2) \dots$

Second order: $P(X_1, \dots, X_T) = P(X_1) \cdot P(X_2 | X_1) \cdot P(X_3 | X_2, X_1) \cdot P(X_4 | X_3, X_2) \dots$

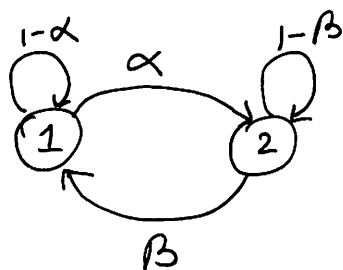
Note: however we can always define a new random variable $Y_t = \{X_t, X_{t+1}\}$

$$P(Y_{t+1} | Y_t) = P(X_{t+2} | X_{t+1}, X_t)$$

Thus without loss of generality we can just focus on first order

If X_t is discrete, a markov chain is completely defined by ② the transition matrix. (Assuming the chain is time invariant).

Consider:



$$A = \begin{bmatrix} 1-\alpha & \alpha \\ \beta & 1-\beta \end{bmatrix}$$

$$A_{ij} = P(X_{t+1}=j | X_t=i)$$

We can further consider the n step transition

$$P(X_{t+n}=j | X_t=i) = \sum_{k=1}^K P(X_{t+m}=k | X_t=i) \cdot P(X_{t+n}=j | X_{t+m}=k)$$

$\Downarrow$

$$A_{ij}(n) = \sum_{k=1}^K A_{ik}(m) \cdot A_{kj}(n-m)$$

$$A(n) = A(m)A(n-m)$$

$$= AA \dots A$$

$$= A^n$$

For some $n > 0$ if $A_{ij}(n) > 0 \Rightarrow$ state j is reachable from state i

$$\pi_t(j) = P(X_t = j)$$

$$\pi_t = \sum_{i=1}^K P(X_{t-1} = i) \cdot P(X_t = j | X_{t-1} = i)$$

$$= \sum_{i=1}^K \pi_{t-1}(i) A_{ij}$$

In matrix notation Let $\pi_t = \{\pi_t(1) \dots \pi_t(K)\} \in \mathbb{R}^{1 \times K}$

$$\pi_t = \pi_{t-1} A$$

After repeating/iterating if we reach a stage where

Note*
Till π_0

$$\pi_t = \pi_{t-1} \text{ i.e. } \pi = \pi A \text{ we say that}$$

the chain has reached its stationary distribution.

ASIDE

Why Do we care about the stationary distribution??

→ Intractable integral. For instance GPC; interested in prediction $P(Y_* = 1 | X_*, Y, X_*, K) = \int P(Y_* | f_*) P(f_* | X_*, K) df_*$

→ Can't compute the integral directly and we made approximated $P(f_* | X_*, Y, X_*, K) \approx \mathcal{N}(\hat{f}, \Sigma)$ and computed the integral.

→ Alternatively, we could evaluate the function at various f_* , and add up the compute the integral numerically

- (4)
- doesn't really scale to high dimensions.
 - what we really want is to sample from the true posterior distribution and use these samples to evaluate the required moments.
 - Setting up a Markov chain whose stationary distribution = posterior distribution, lets us do so.
-

$$\pi = \pi A$$

$$\Rightarrow A^T \pi^T = \pi^T \Rightarrow A^T v = v$$

Thus given a Markov chain; its stationary distribution can be found by finding the eigenvector of A which has an eigenvalue $= 1$.

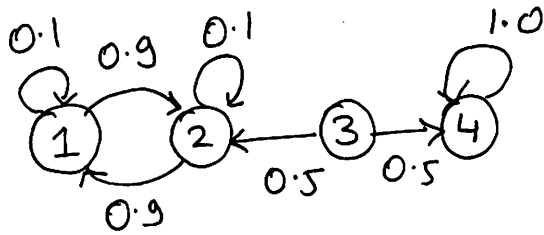
From PERRON-FROBENIUS Theorem,

$\Rightarrow$ for a row stochastic matrix the eigenvalue 1 is dominant. i.e. $\lambda_i = 1$ & $\lambda_j: j \neq i < \infty \quad \forall j$

$\Rightarrow$ Thus we only need to find the dominant eigenvector; efficient tools for this exist ex "Power method"

When do unique stationary distributions exist?

⑤



$\Rightarrow$ If we start at node ④ we are stuck. $(0, 0, 0, 1)$

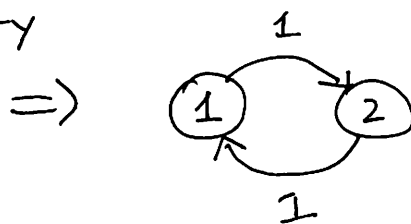
$\Rightarrow$ Starting at node ③ we could end up in either $(0.5, 0.5, 0, 0)$ or $(0, 0, 0, 1)$

Thus the above chain has no unique stationary distribution.

But both connected components do.

IRREDUCIBILITY $\Rightarrow$ All states in the chain must be reachable

APERIODICITY



if we start at state 1
we can be in state 2 only
in the $\{2, 4, 6, \dots\}$ time steps

Period of ② $\Rightarrow 1$

~~Stationary~~ Limiting distribution
would depend on which state we
start. Thus no stationary
distribution.

If the period of all states in the chain is 1 the chain (6) is aperiodic.

Intuitively, this means we can visit a state i at irregular times.

⇒ An irreducible and aperiodic ^{→ # of states is finite.} finite markov chain ~~is~~ has a unique stationary distribution.

A quick test: — Chain is singly connected and each state has a self loop. (Sufficient not necessary)

DETAILED BALANCE test: —

$$P(X_t=i) P(X_t=j | X_{t-1}=i) = P(X_{t-1}=j) P(X_t=i | X_{t-1}=j)$$

$$\Rightarrow \pi_i A_{ij} = \pi_j A_{ji}$$

detailed balance equation.

If a markov chain satisfies the detailed balance equation wrt π then π is a stationary distribution of A .

$$\begin{aligned} \sum_i P(X_{t-1}=i) P(X_t=j | X_{t-1}=i) &= \sum_i P(X_{t-1}=j) P(X_t=i | X_{t-1}=j) \\ &= \pi_j \end{aligned}$$

Given a desired π , a transition matrix A can be constructed to satisfy the detailed balance equations.