

Chapter 2

Integer Programming

Paragraph 1

Total Unimodularity

What we did so far

- We studied algorithms for solving linear programs
 - Simplex (primal, dual, and primal-dual)
 - Ellipsoid Method (proving LP is in P)
 - Interior Point Algorithms
- We looked into standard formats that interface between the LPs that we want to solve and the available programs that we can use to solve our problems.
 - MPS
 - LP
 - CPLEX callable library

How Powerful is Linear Programming?

- LPs can be solved in polynomial time.
- Is that good news or bad news?
 - Of course, it is good news, because it means that we can efficiently solve a very large class of problems. 😊
 - On the other hand, if we believe that $NP \neq P$, it also means that we can solve no NP-hard problems. ☹️
- In order to model NP-hard problems as well, we need more expressiveness:
 - We need to be able to make real discrete decisions.
 - By allowing one more type of constraint, we can achieve this expressiveness.
 - The constraint being: Let some or all variables be **integer**.

Integer Programming

- Standard form: Minimize $c^T x$ such that
 - $Ax = b$
 - $x \geq 0$
 - x_i integer for all $i \in I \subseteq \{1, \dots, n\}$.
- Canonical form analogously to LP.
- Can we solve NP-hard problems now? Model 3-SAT:
 - One binary variable $x_i \in \{0, 1\}$ for every X_i in the formula.
 - For each clause $(X_i \vee \neg X_j \vee X_k)$ in the formula add a constraint
 - $x_i + (1-x_j) + x_k \geq 1 \Leftrightarrow x_i - x_j + x_k \geq 0$
 - For any clause: $\bigvee_{i \in I} X_i \vee \bigvee_{j \in J} \neg X_j$ is modeled as
 - $\sum_{i \in I} x_i - \sum_{j \in J} x_j \geq 1 - |J|$

Integer Programming

- Model the Knapsack Problem
 - Max $p^T x$
 - $w^T x \leq C$
 - $x \in \{0, 1\}^n$
- Model the Shortest Path Problem
 - Min $\sum_{(i,j) \in E} c_{ij} x_{ij}$
 - $\sum_{(s,j) \in E} x_{sj} - \sum_{(i,s) \in E} x_{is} = 1$ for the source node s
 - $\sum_{(k,j) \in E} x_{kj} - \sum_{(i,k) \in E} x_{ik} = 0$ for all nodes $s \neq k \neq t$
 - $\sum_{(i,t) \in E} x_{it} - \sum_{(t,j) \in E} x_{tj} = -1$ for the sink node t
 - $x_{ij} \in \{0, 1\}$ for all $(i,j) \in E$

Integer Programming

- Model the Assignment Problem
 - Min $\sum_{(i,j) \in E} C_{ij} X_{ij}$
 - $\sum_j x_{ij} = 1$ for all jobs j
 - $\sum_j x_{ij} = 1$ for all machines i
 - $x \in \{0, 1\}^n$
- Model the Transportation Problem
 - Min $\sum_{fr} C_{fr} X_{fr}$
 - $\forall_f X_{fr} = D_r$ for all retailers r
 - $\forall_r X_{fr} \leq S_f$ for all factories f
 - x integer

Integer Programming

- Model Graph Bisection
 - Min $\sum_{(i,j) \in E} z_{ij}$
 - $z_{ij} \geq x_i - x_j$
 - $z_{ij} \geq x_j - x_i$
 - $\sum_i x_i = n/2$
 - $z_{ij}, x_i \in \{0, 1\}$

Complexity

- Some of the above problems are
 - NP-hard but approximable (like KP), some are even
 - NP-hard in the strong sense (like Graph Bisection),
 - but others are poly-time solvable (like the Shortest Path Problem).
- Can we model problems like Shortest Path as an LP? More generally: Under what circumstances is an LP solution guaranteed to be integer?

Total Unimodularity

- The solution to an LP returned by the simplex algorithm is $x^T = (b^T A_B^{-T}, 0_N^T)$.
- Consider the quadratic system $By = b$ (where we think of $B = A_B$ and $y = x_B$, of course). Denote with B_b^j the matrix B where the j 'th column is replaced by b , i.e. $B_b^j = (B_1, \dots, B_{j-1}, b, B_{j+1}, \dots, B_m)$.
- According to Cramer's rule, we have that
 - $y_j = |B_b^j| / |B|$, where $|X|$ denotes the determinant of matrix X .

Total Unimodularity

- Denote with B^{ij} the matrix that evolves from B when deleting the i th row and the j th column.
- We can compute the determinant of B_b^j in the following way:
 - $|B_b^j| = \sum_i (-1)^{i+j} b_i |B^{ij}|.$
- Consequently, when
 - $|B| = -1$ or $|B| = 1$ and
 - $|B^{ij}| \in \{-1, 0, 1\}$ for all i, j ,then y is integer.

Total Unimodularity

- Definition
 - A submatrix of a matrix A is any square matrix that evolves from A by deleting some columns and rows from A .
 - A matrix A is called totally unimodular (TU), iff the determinants of all submatrices of A are either -1 , 0 , or 1 .
- Theorem
 - A polytope $P = \{ x \mid Ax = b, x \geq 0 \}$ with A TU and b integer has only integer basic solutions.
 - An IP in standard form over a TU matrix and with integer right hand side is solvable in polynomial time.
 - Any IP over a TU matrix and with integer right hand side is solvable in polynomial time.

Total Unimodularity

- Theorem [TU Partition]
 - A is TU iff for all $I \subseteq \{1, \dots, m\}$ there exists a partition of I into K and L such that for all $j \in \{1, \dots, n\}$ it holds that $|\sum_{i \in K} a_{ij} - \sum_{i \in L} a_{ij}| \leq 1$.
- Proof: See for instance Nemhauser/Wolsey “Integer and Combinatorial Optimization” #543.
- Corollary
 - A is TU if
 - it only has at most two non-zero entries 1 or -1 in every column, and
 - for all columns with two non-zero coefficients, the column-sum is 0.

Total Unimodularity

- Theorem
 - Given A TU. Then, the following matrices are TU:
 1. A^T is TU.
 2. (A, I_m) is TU.
 3. $(A, -A)$ is TU.
 4. A^{-1} (if A is square and non-singular).
 - A remains TU under the following operations:
 5. Deleting or duplicating a row or column.
 6. Multiplying a row or column with -1 .
 7. Permuting rows or columns.
 8. Performing a pivot operation on A .

Total Unimodularity

- Proof:

1. $|X| = |X^T|$.

2. Any submatrix of (A,I) can be row-permuted so that it takes form

$$\boxed{C = \begin{pmatrix} B & 0 \\ D & I_k \end{pmatrix}} \quad \text{Therefore, } |C| = |B|.$$

3. Implied by 5 and 6.

4. Implied by 2 and 8.

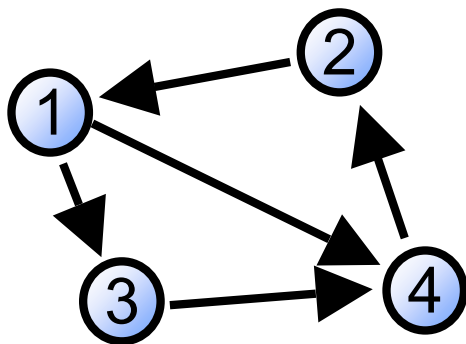
5. Any non-singular submatrix only contains one of the two rows or columns in question.

6. and 7. Follows from the TU Partition Theorem.

8. Exercise

Graph LPs

- A node-arc incidence matrix has a row for each node and a column for each edge of a given graph. Every column belonging to edge $(i,j) \in E$ contains exactly two non-zero entries: a -1 in row i and a 1 in row j .



-1	-1	1		
		-1		1
1			-1	
	1		1	-1

Assignments

- An assignment matrix looks like this:

1	1	1							J ₁
			1	1	1				
						1	1	1	
1			1			1			J ₂
	1			1			1		
		1			1			1	

Total Unimodularity

- Corollary
 - If A is a node-arc incidence matrix, then it is TU. This implies that the Shortest Path Problem and the Transportation Problem are in P . So are all kinds of flow problems.
 - If A is an assignment matrix, then it is TU. This implies that the Assignment Problem is in P .

Thank you!

