

Introduction to Machine Learning

Brown University CSCI 1950-F, Spring 2012
Prof. Erik Sudderth

Lecture 18:
Clustering & K-Means Algorithm
EM for Gaussian Mixture Models

Many figures courtesy Kevin Murphy's textbook,
Machine Learning: A Probabilistic Perspective

On to Unsupervised Learning

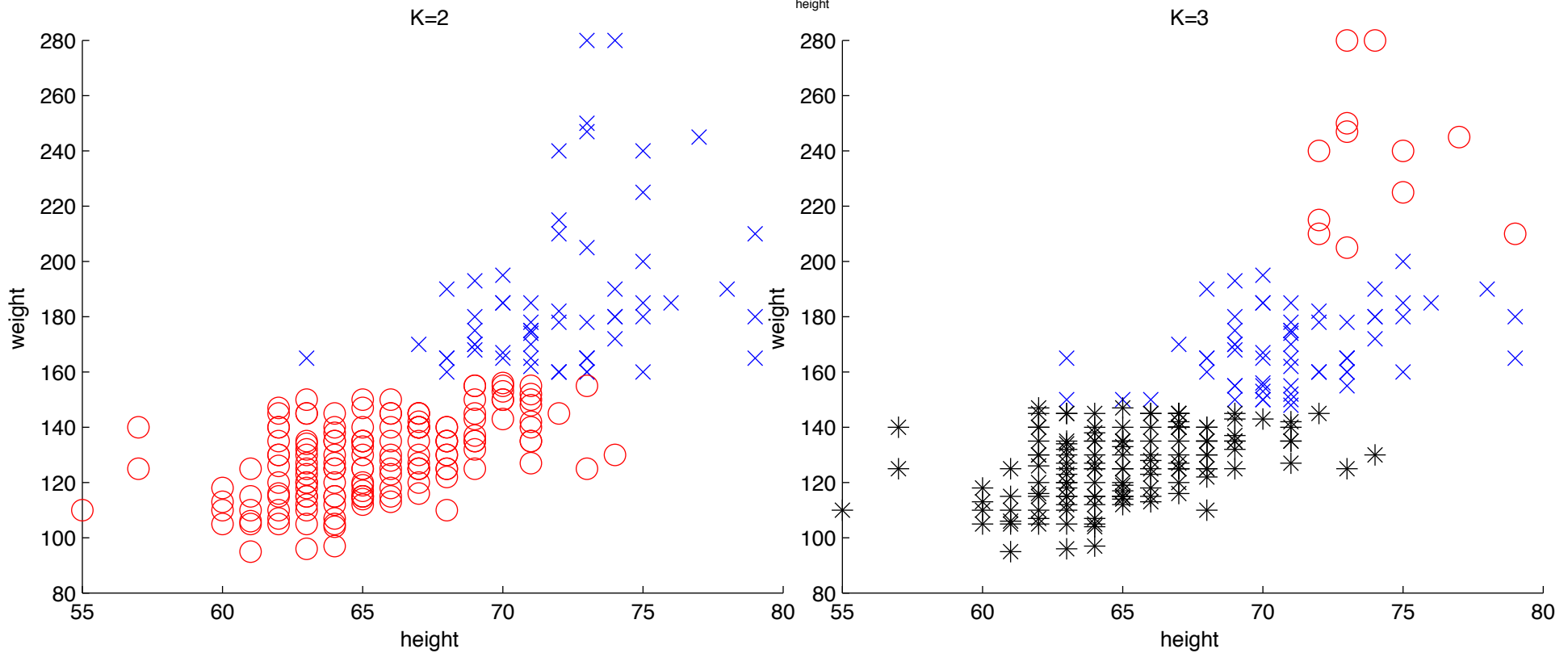
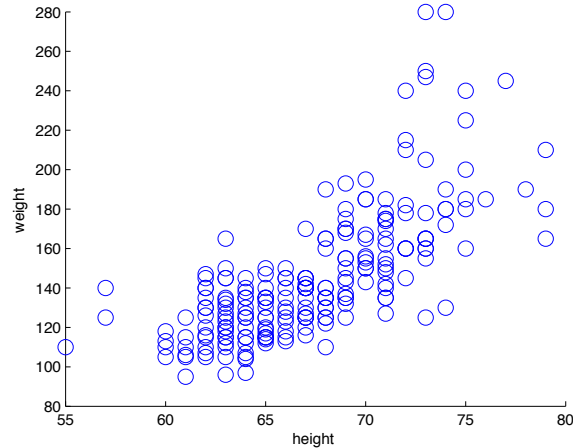
Supervised Learning

Unsupervised Learning

<i>Discrete</i>	classification or categorization	clustering
	regression	dimensionality reduction

- **Goal:** Infer label/response y given only features x
- **Classical:** Find latent variables y good for *compression* of x
- **Probabilistic learning:** Estimate parameters of joint distribution $p(x,y)$ which *maximize marginal probability* $p(x)$

Clustering can be Ambiguous



K-Means Objective: Compression

- Observed feature vectors: $x_i \in \mathbb{R}^d, \quad i = 1, 2, \dots, N$
- Hidden cluster labels: $z_i \in \{1, 2, \dots, K\}, \quad i = 1, 2, \dots, N$
- Hidden cluster centers: $\mu_k \in \mathbb{R}^d, \quad k = 1, 2, \dots, K$

$$J(z, \mu \mid x, K) = \sum_{k=1}^K \sum_{i \mid z_i=k} ||x_i - \mu_k||^2 = \sum_{i=1}^N ||x_i - \mu_{z_i}||^2$$

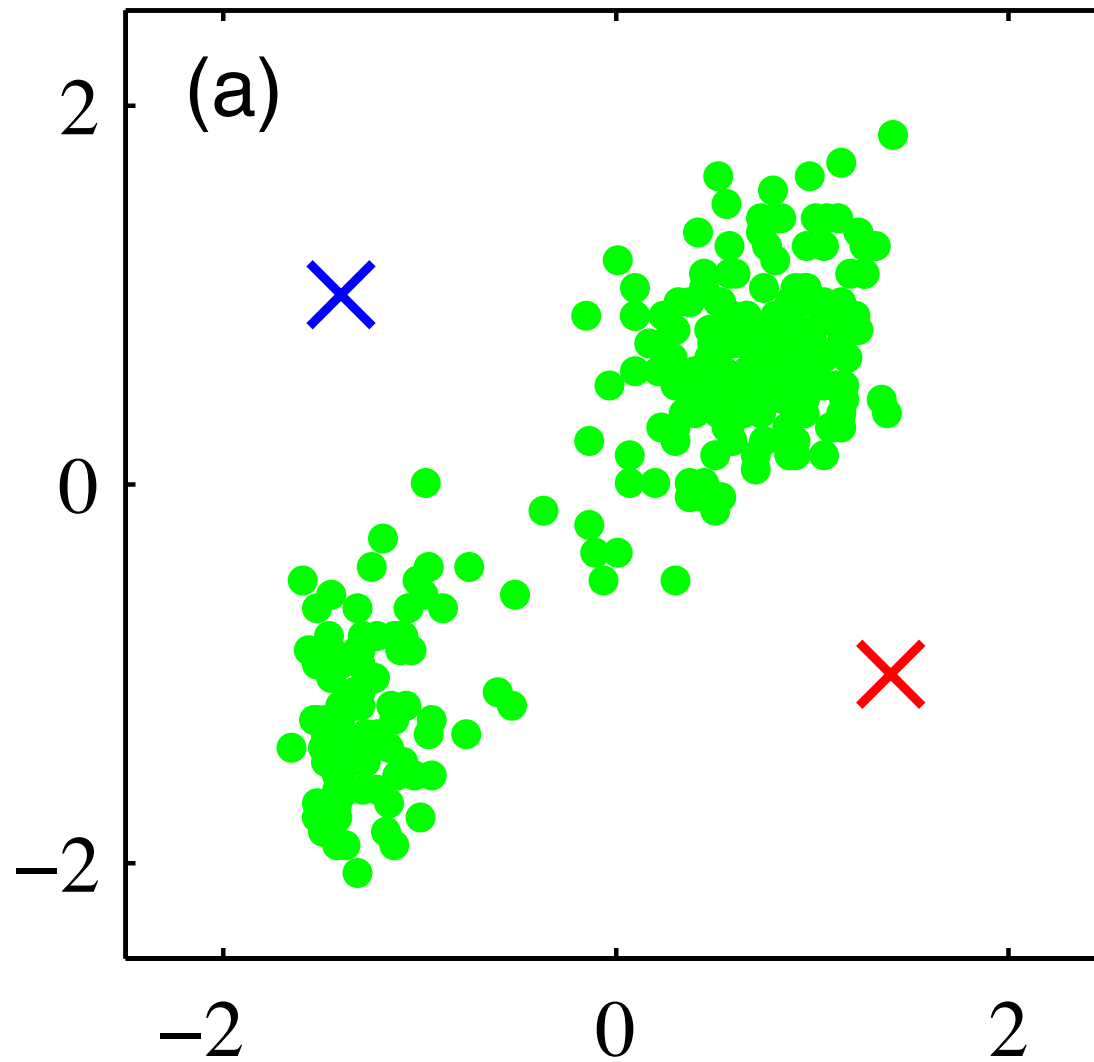
$$J(z, \mu \mid x, K) = \sum_{k=1}^K \sum_{i=1}^N r_{ik} ||x_i - \mu_k||^2 \quad r_{ik} = \mathbb{I}(z_i = k)$$

*K-Means
alternates
between*

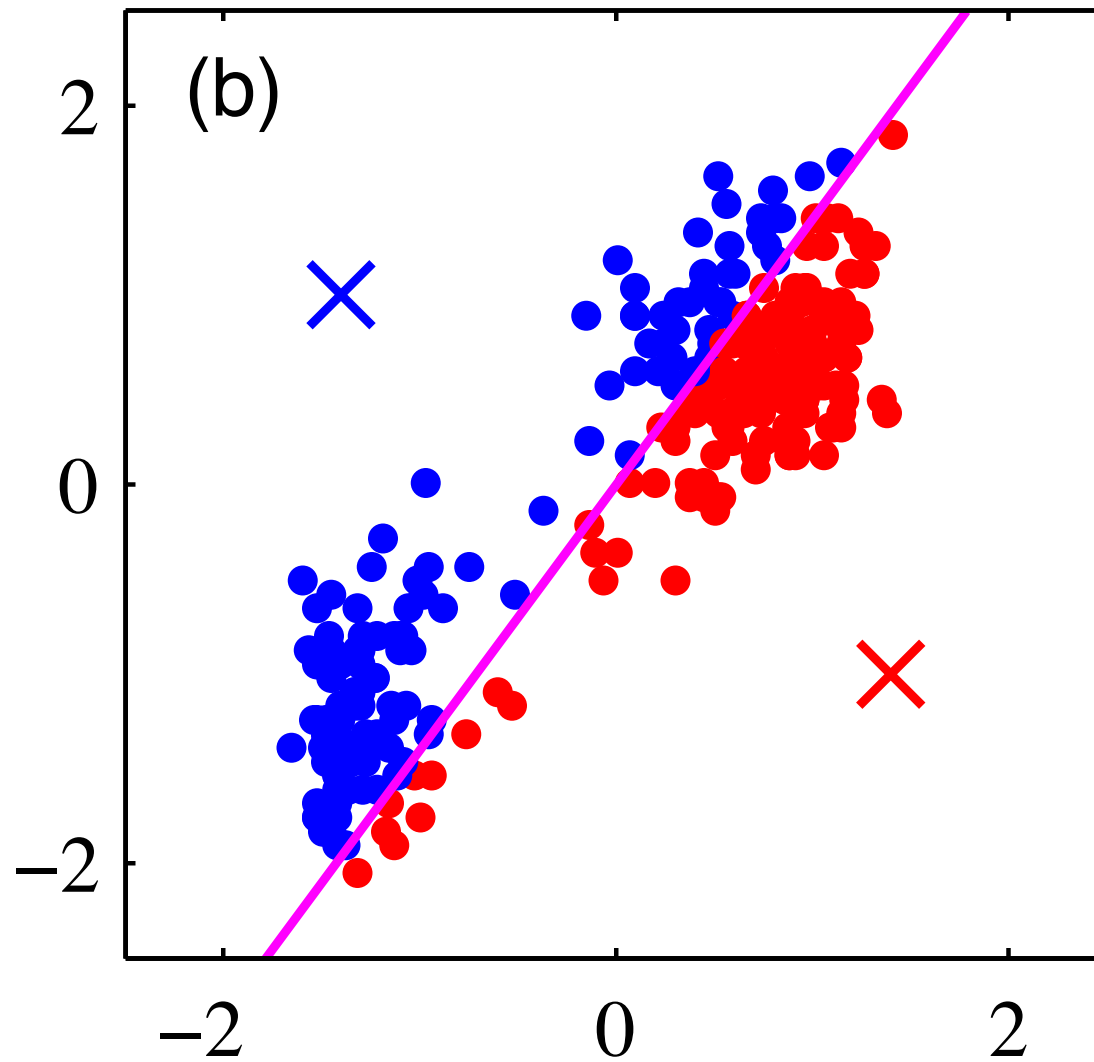
$$z^{(t)} = \arg \min_z J(z, \mu^{(t-1)} \mid x, K)$$

$$\mu^{(t)} = \arg \min_{\mu} J(z^{(t)}, \mu \mid x, K)$$

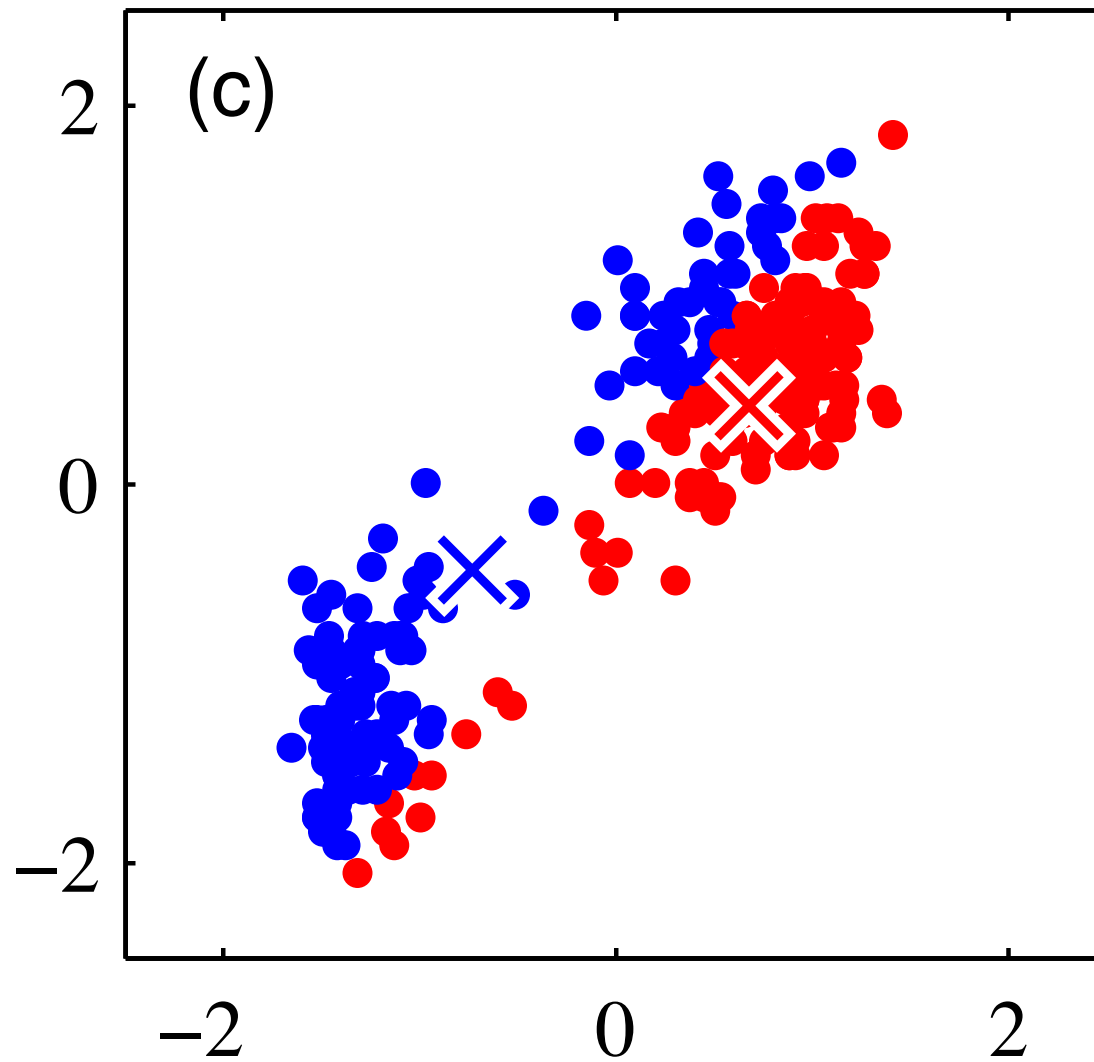
K-Means Algorithm



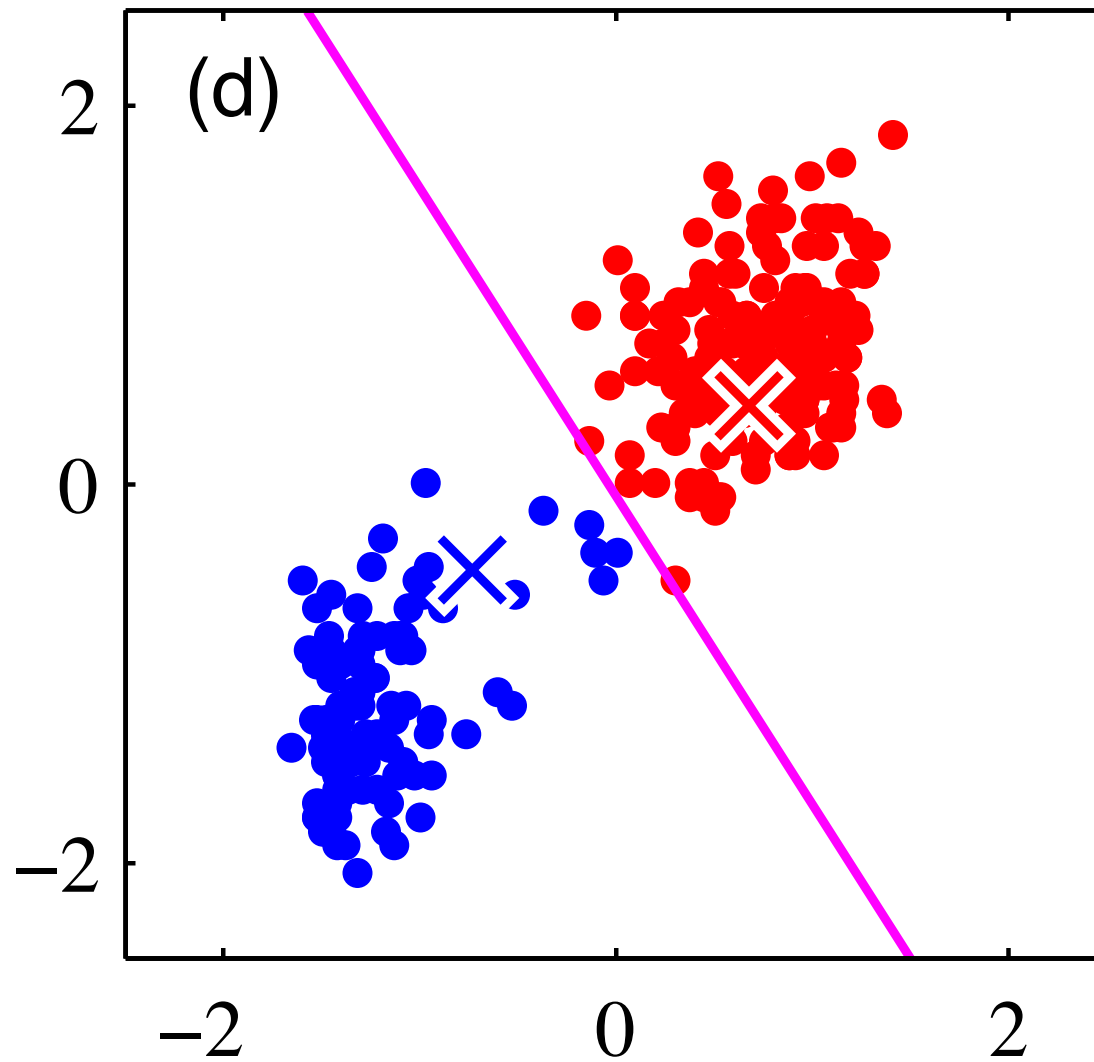
K-Means Algorithm



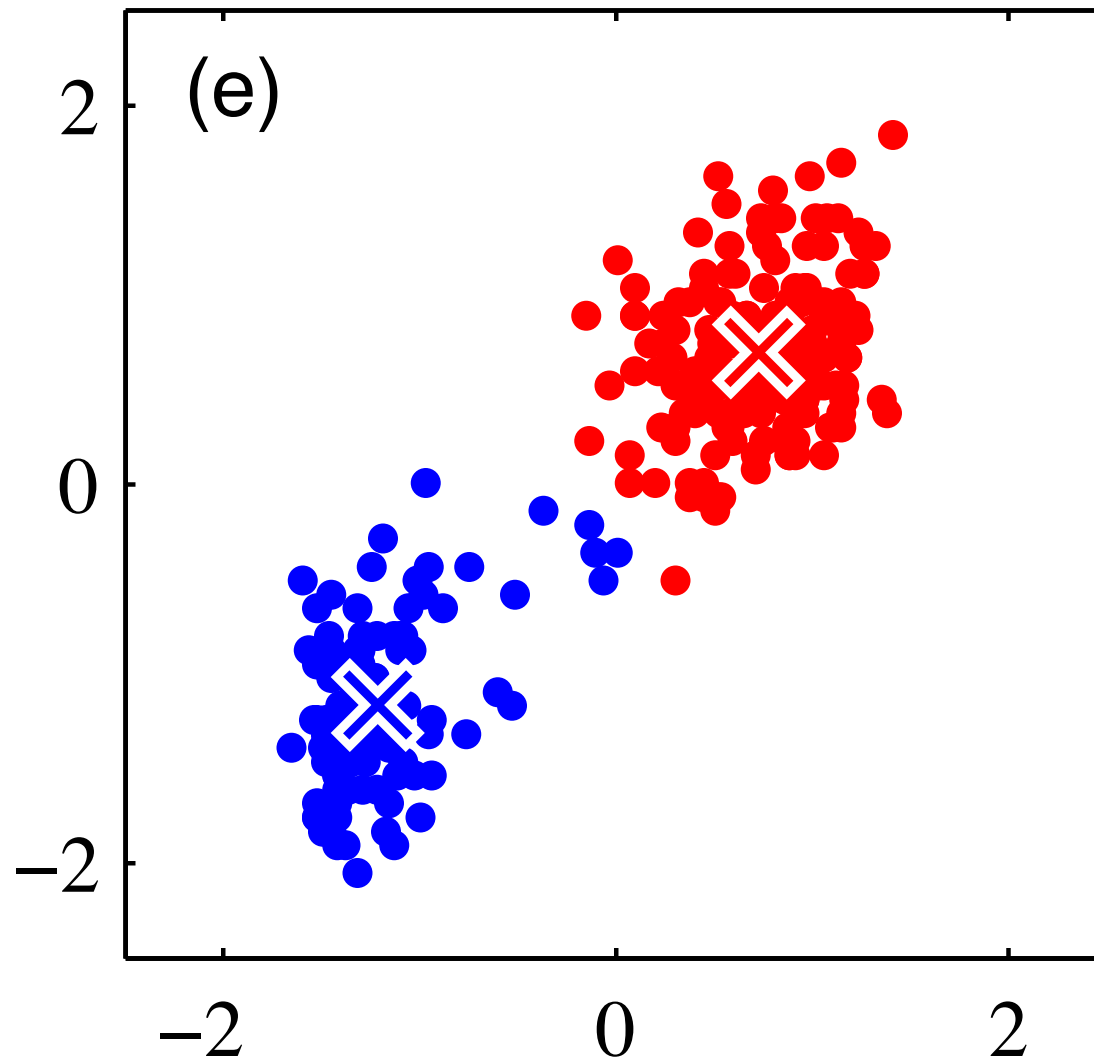
K-Means Algorithm



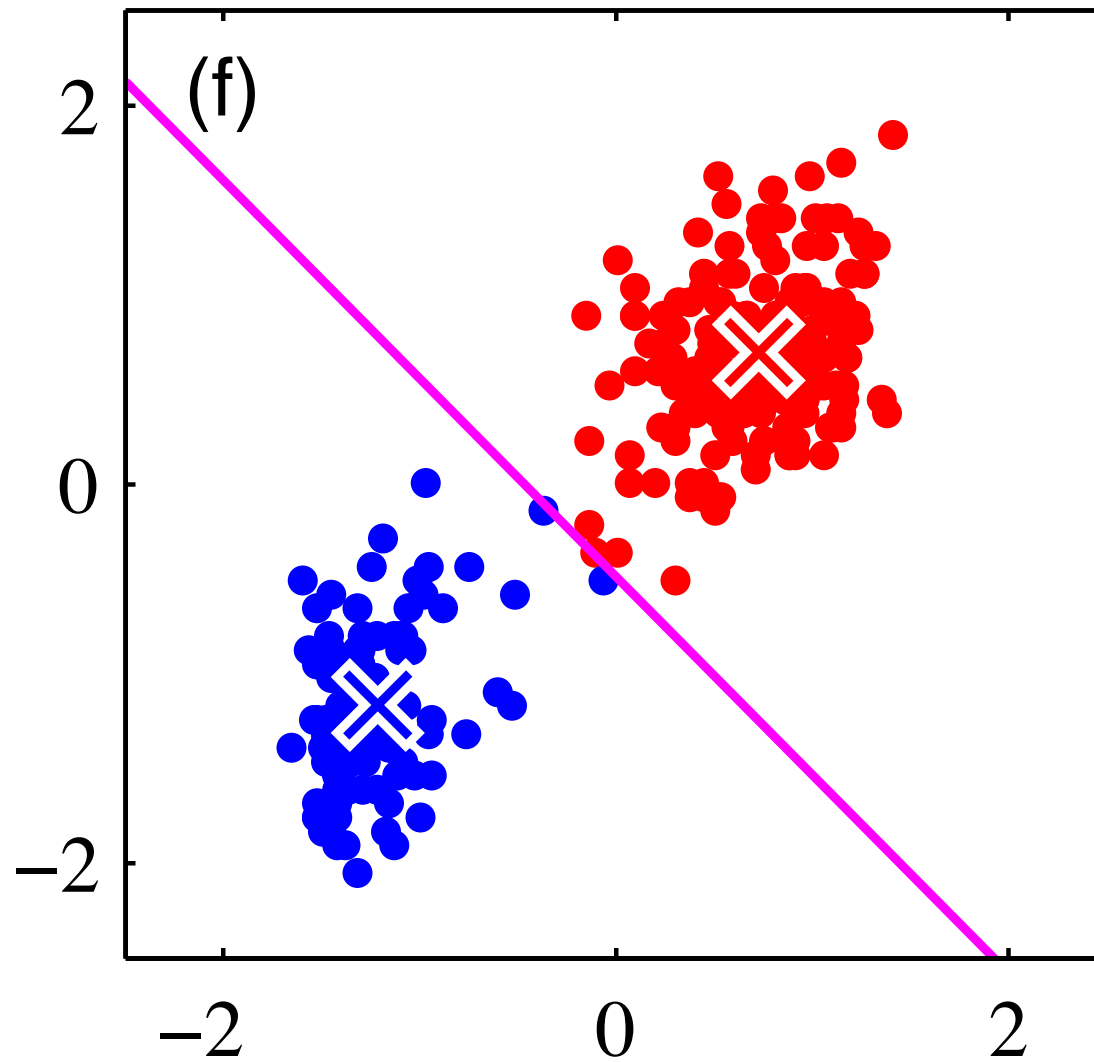
K-Means Algorithm



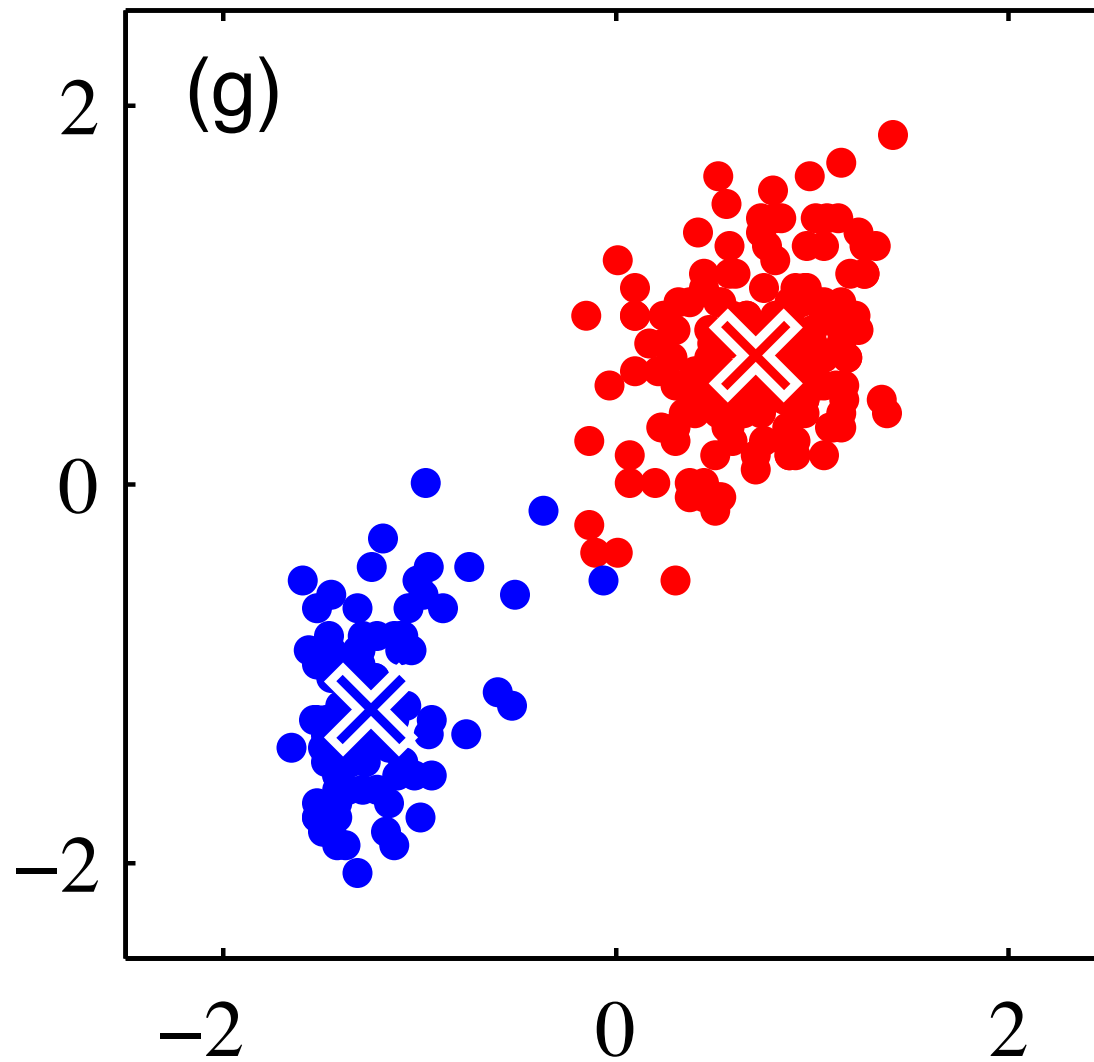
K-Means Algorithm



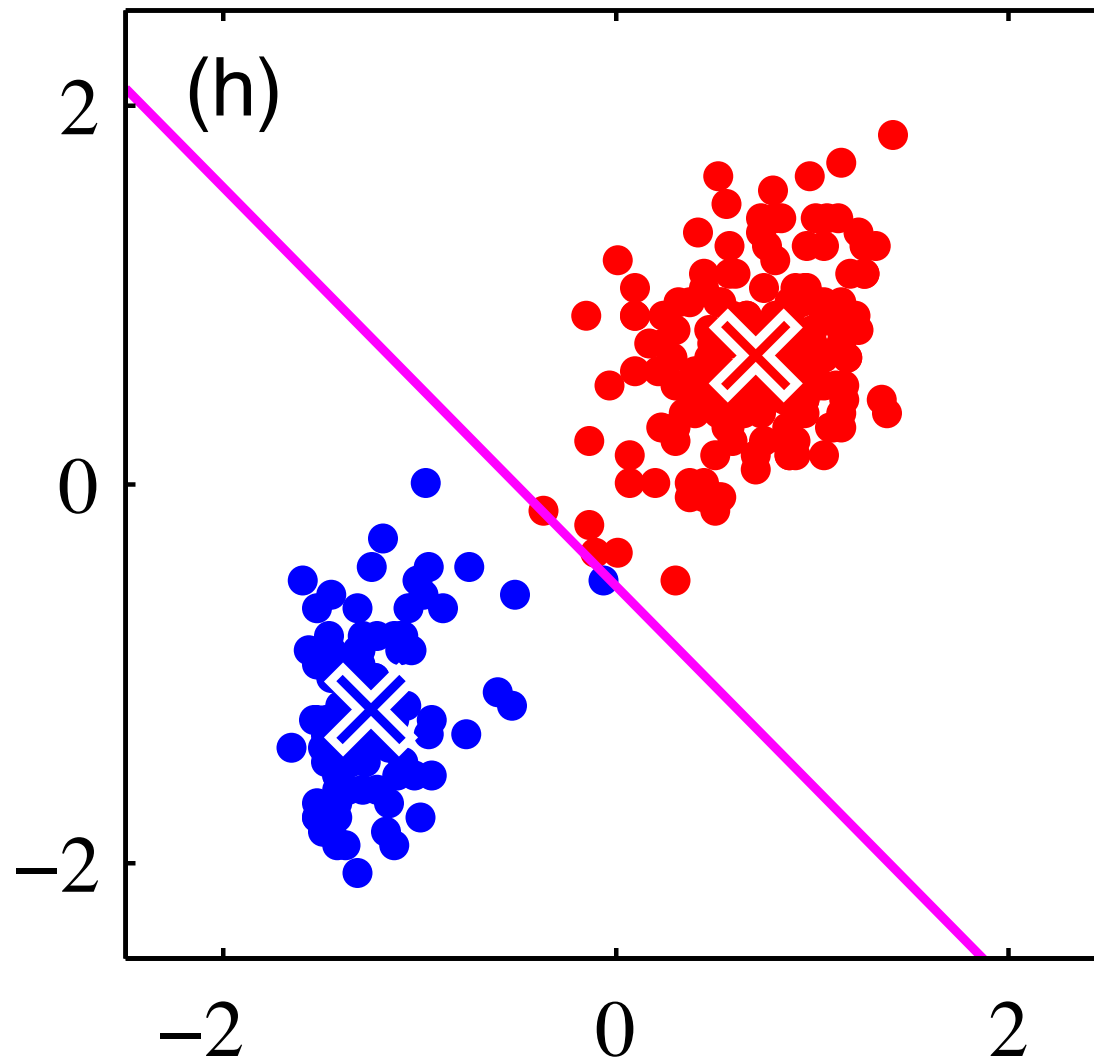
K-Means Algorithm



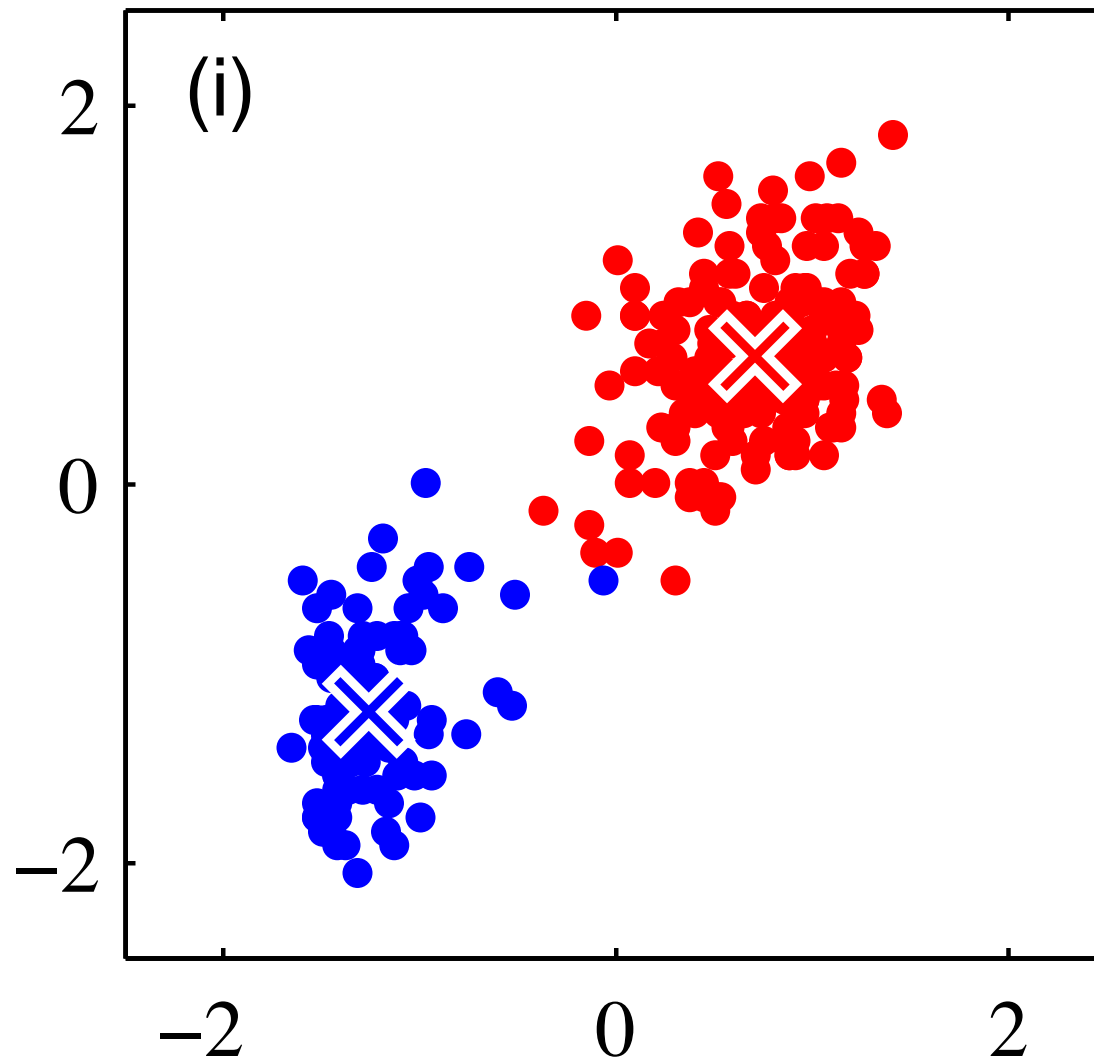
K-Means Algorithm



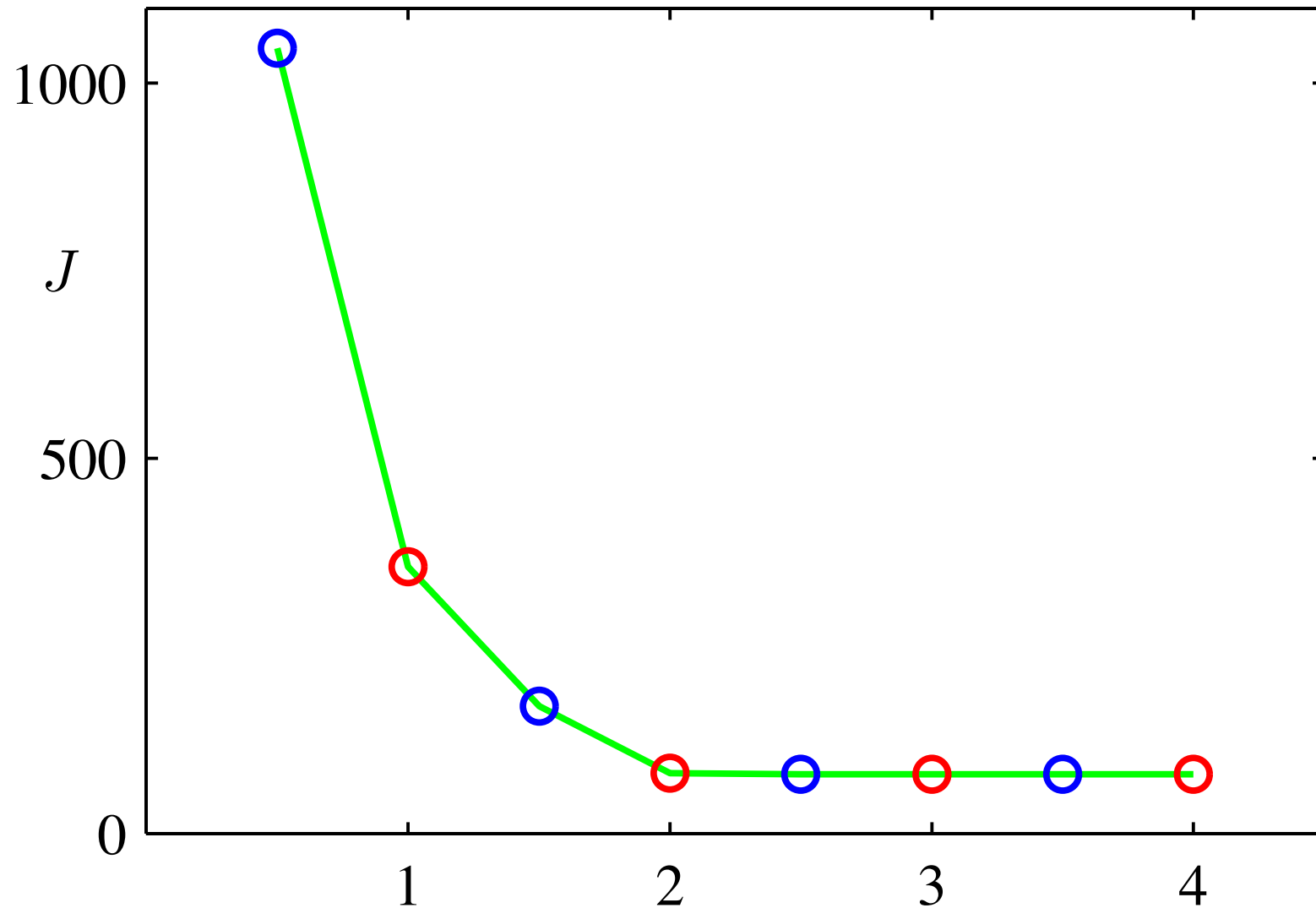
K-Means Algorithm



K-Means Algorithm

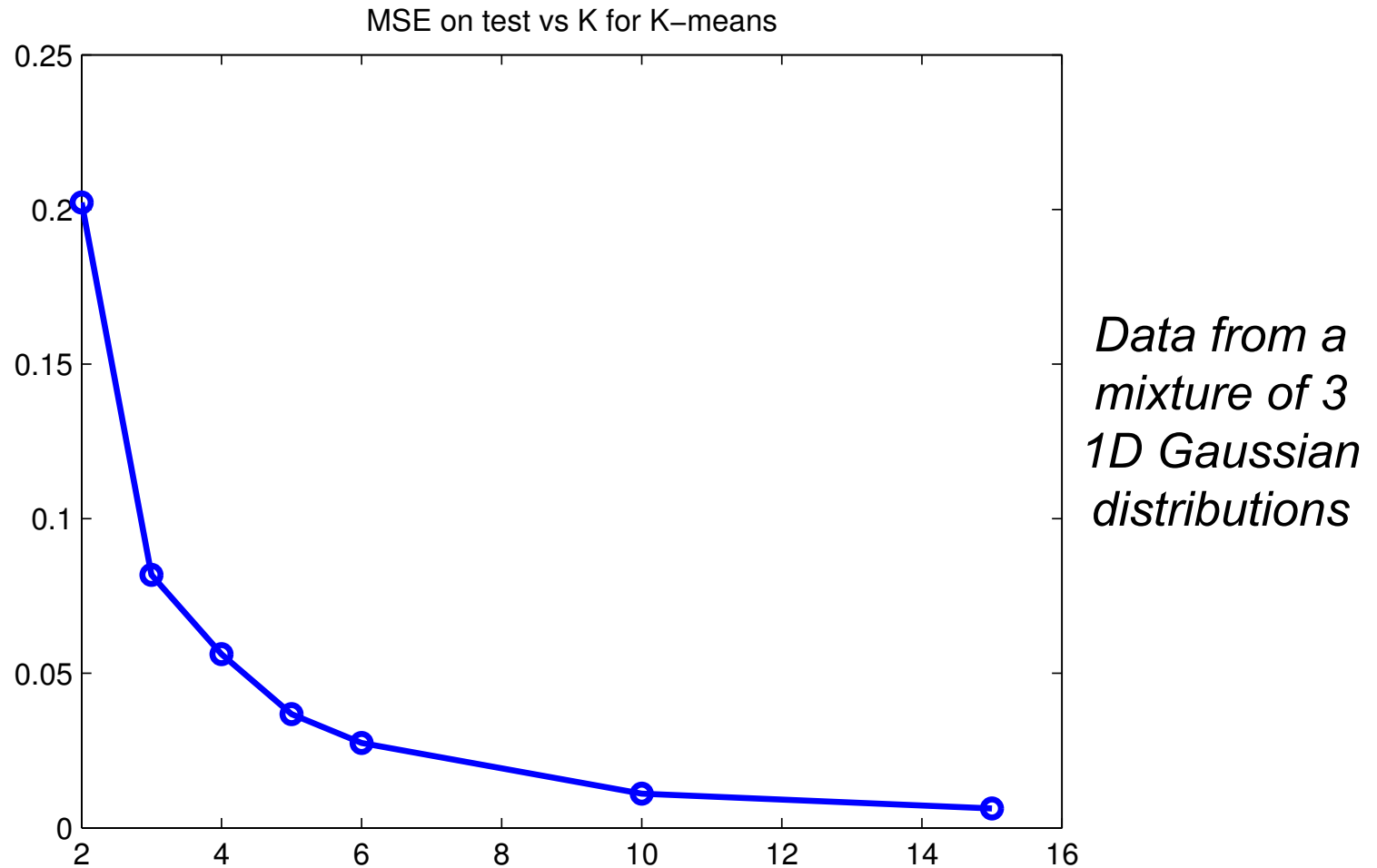


Reconstruction Error versus Iteration



C. Bishop, Pattern Recognition & Machine Learning

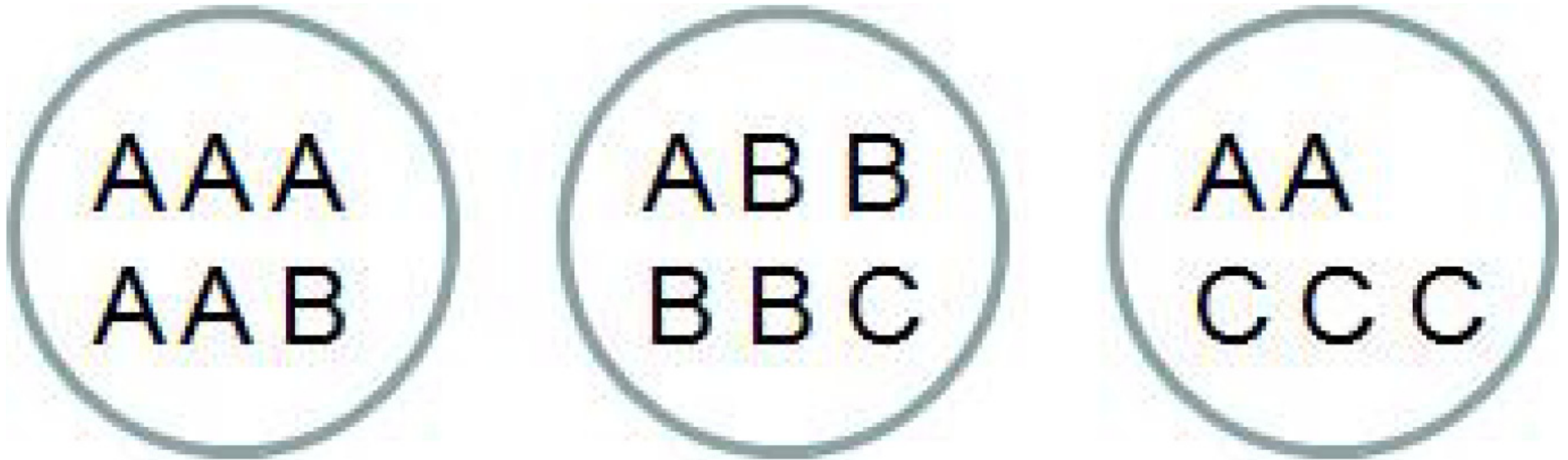
Test Error versus K



For compressing new data, more codewords is always better.

Cross-validation fails for unsupervised learning!

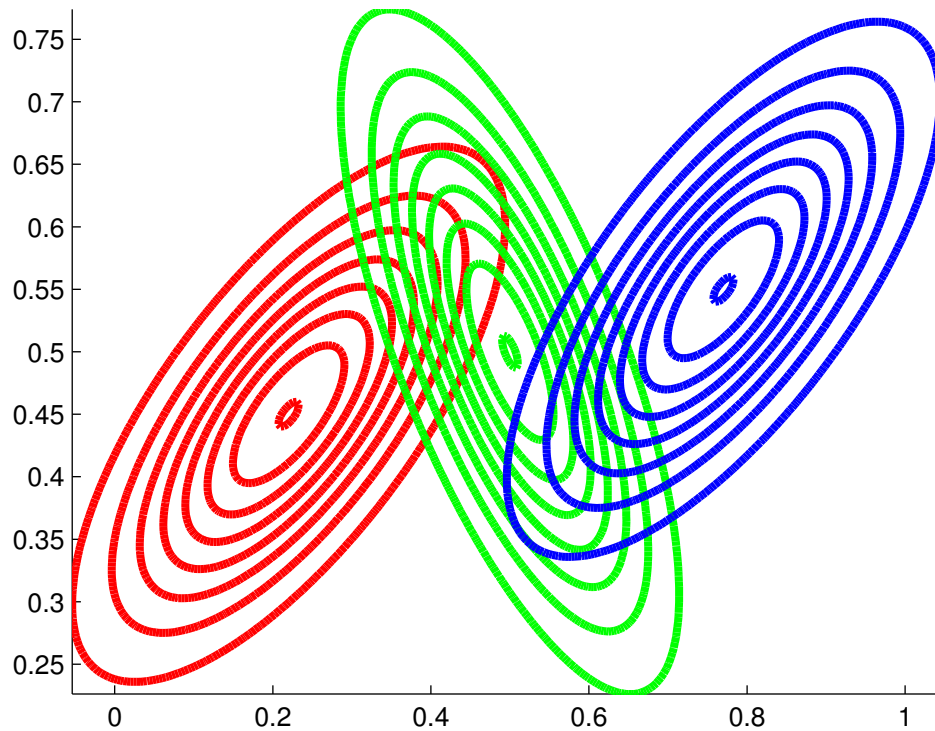
Clustering Evaluation: Rand Index



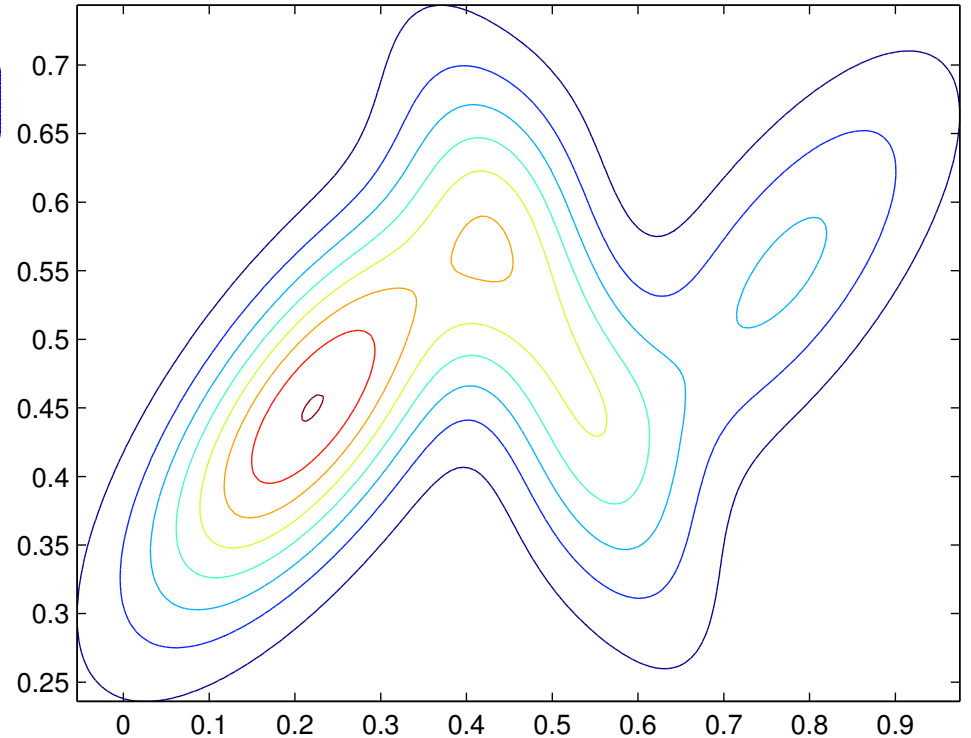
$$R := \frac{TP + TN}{TP + FP + FN + TN}$$

Consider all pairs of data points, and count fraction where hypothesized and target clusterings agree

Gaussian Mixture Models

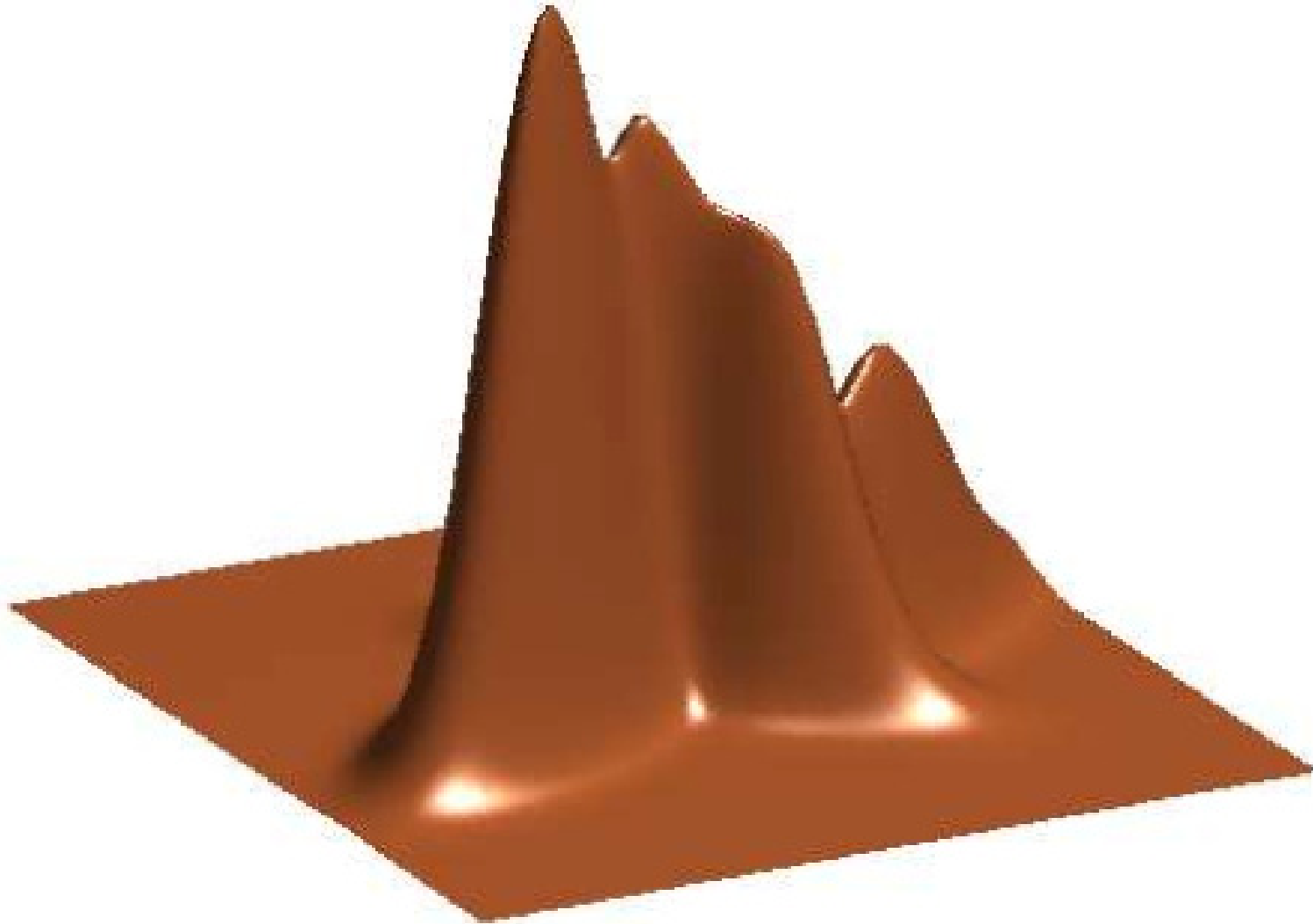


*Mixture of 3 Gaussian
Distributions in 2D*



*Contour Plot of Joint Density,
Marginalizing Cluster Assignments*

Gaussian Mixture Models



*Surface Plot of Joint Density,
Marginalizing Cluster Assignments*

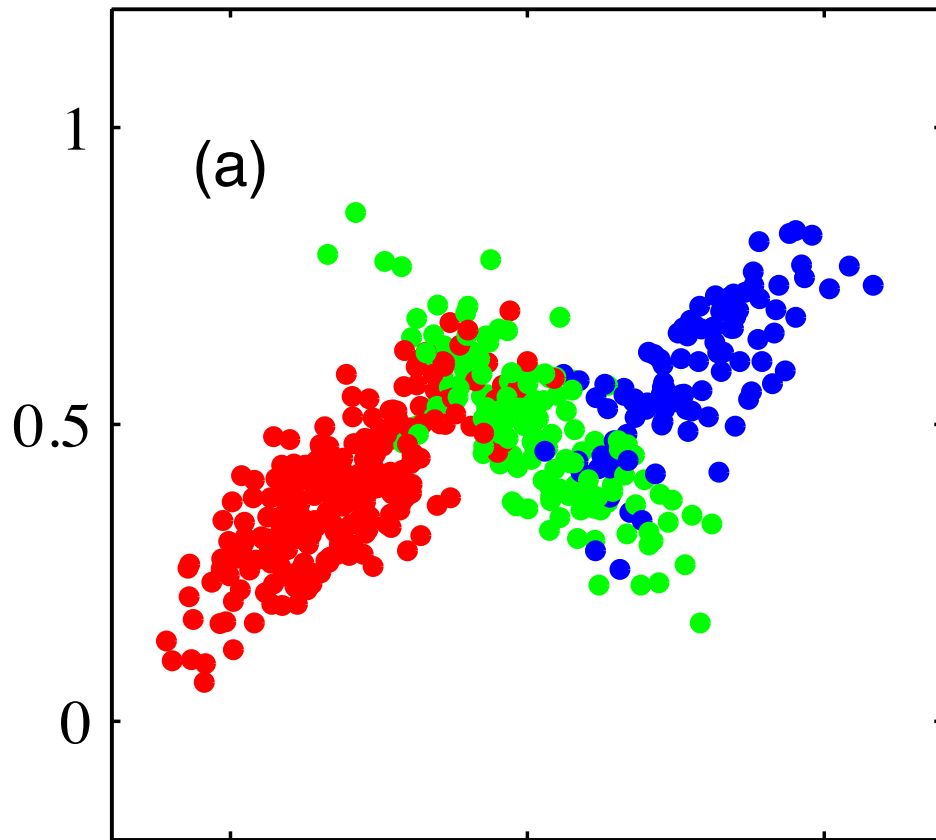
Gaussian Mixture Models

- Observed feature vectors: $x_i \in \mathbb{R}^d, \quad i = 1, 2, \dots, N$
- Hidden cluster labels: $z_i \in \{1, 2, \dots, K\}, \quad i = 1, 2, \dots, N$
- Hidden mixture means: $\mu_k \in \mathbb{R}^d, \quad k = 1, 2, \dots, K$
- Hidden mixture covariances: $\Sigma_k \in \mathbb{R}^{d \times d}, \quad k = 1, 2, \dots, K$
- Hidden mixture probabilities: $\pi_k, \quad \sum_{k=1}^K \pi_k = 1$
- Gaussian mixture marginal likelihood:

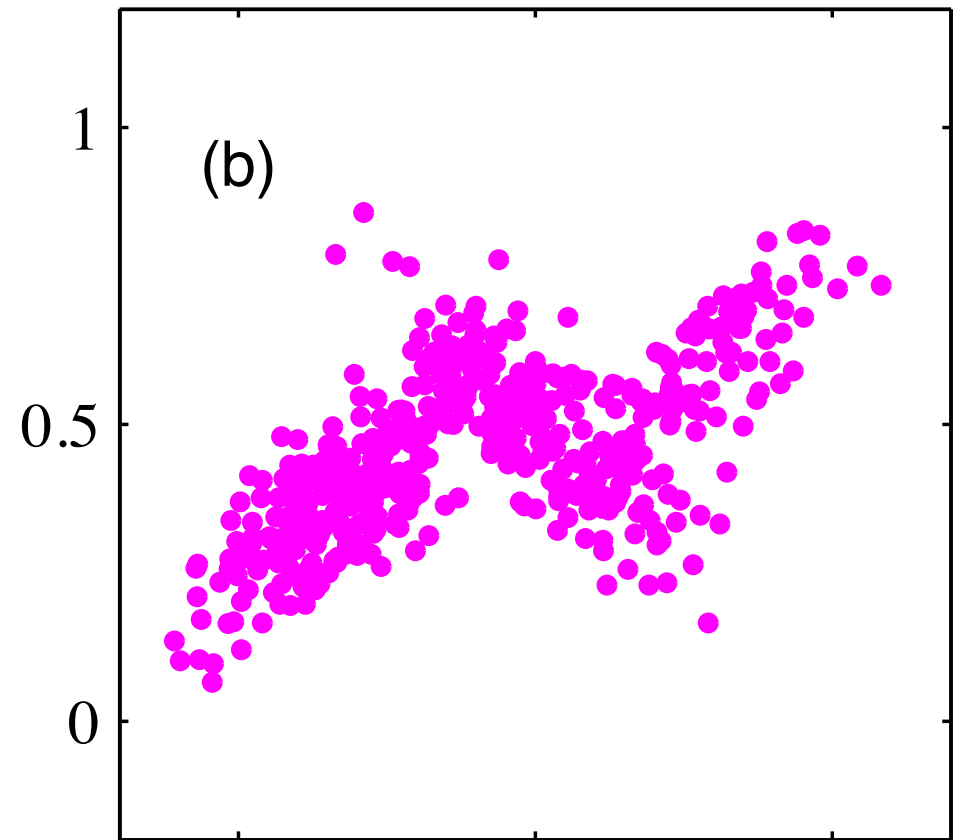
$$p(x_i \mid \pi, \mu, \Sigma) = \sum_{z_i=1}^K \pi_{z_i} \mathcal{N}(x_i \mid \mu_{z_i}, \Sigma_{z_i})$$

$$p(x_i \mid z_i, \pi, \mu, \Sigma) = \mathcal{N}(x_i \mid \mu_{z_i}, \Sigma_{z_i})$$

Fitting Gaussian Mixtures

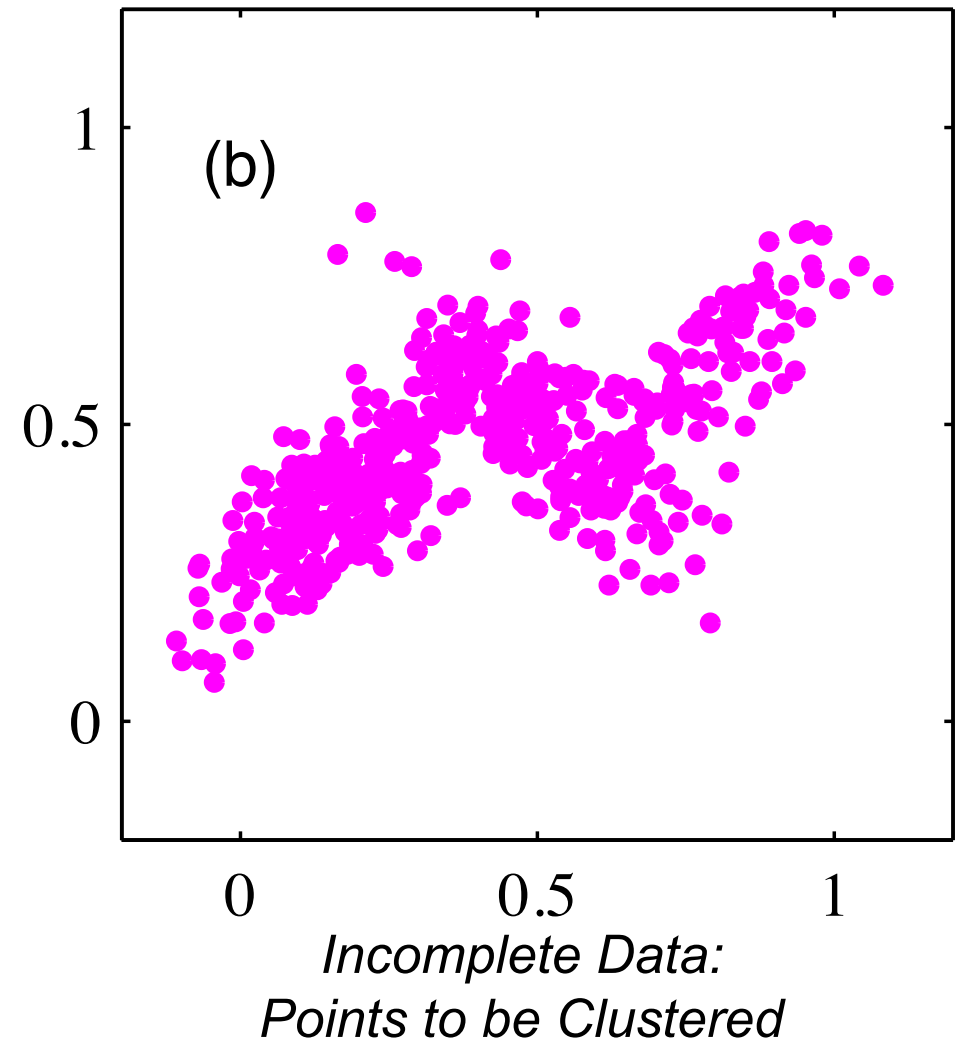
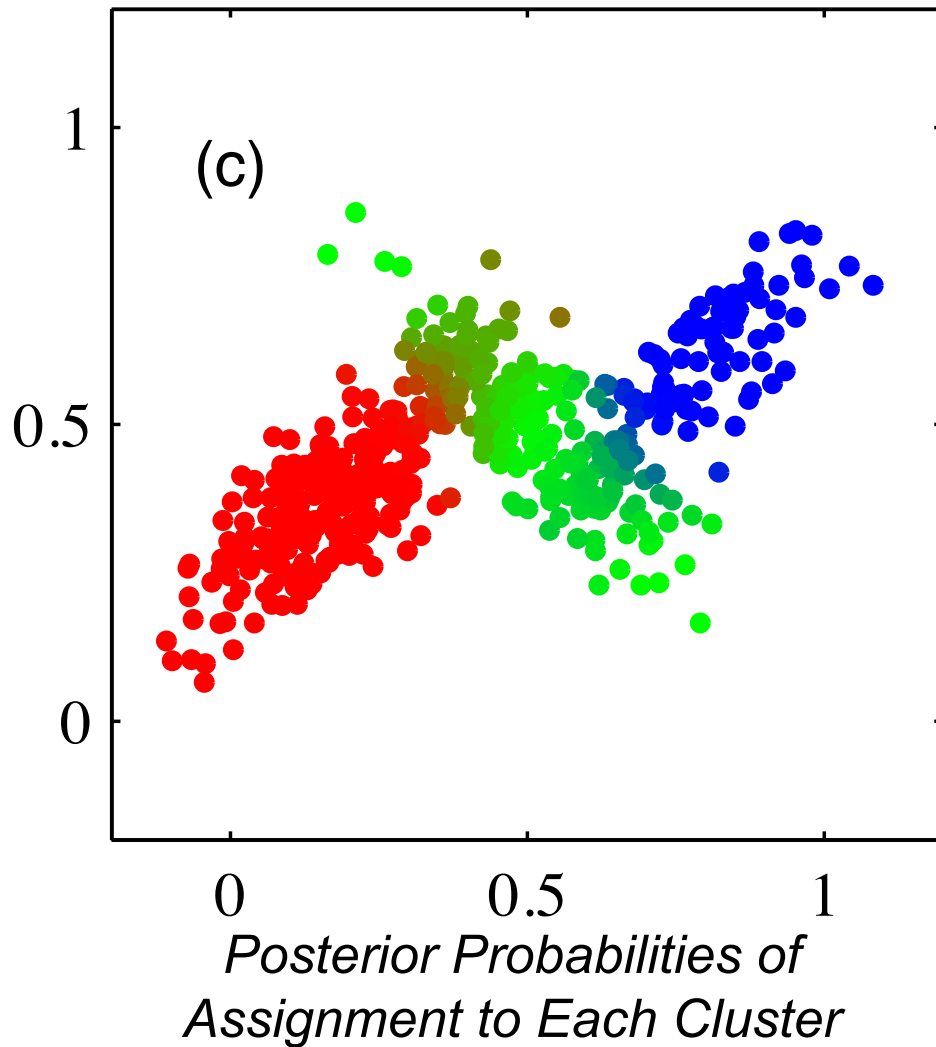


*Complete Data Labeled
by True Cluster Assignments*

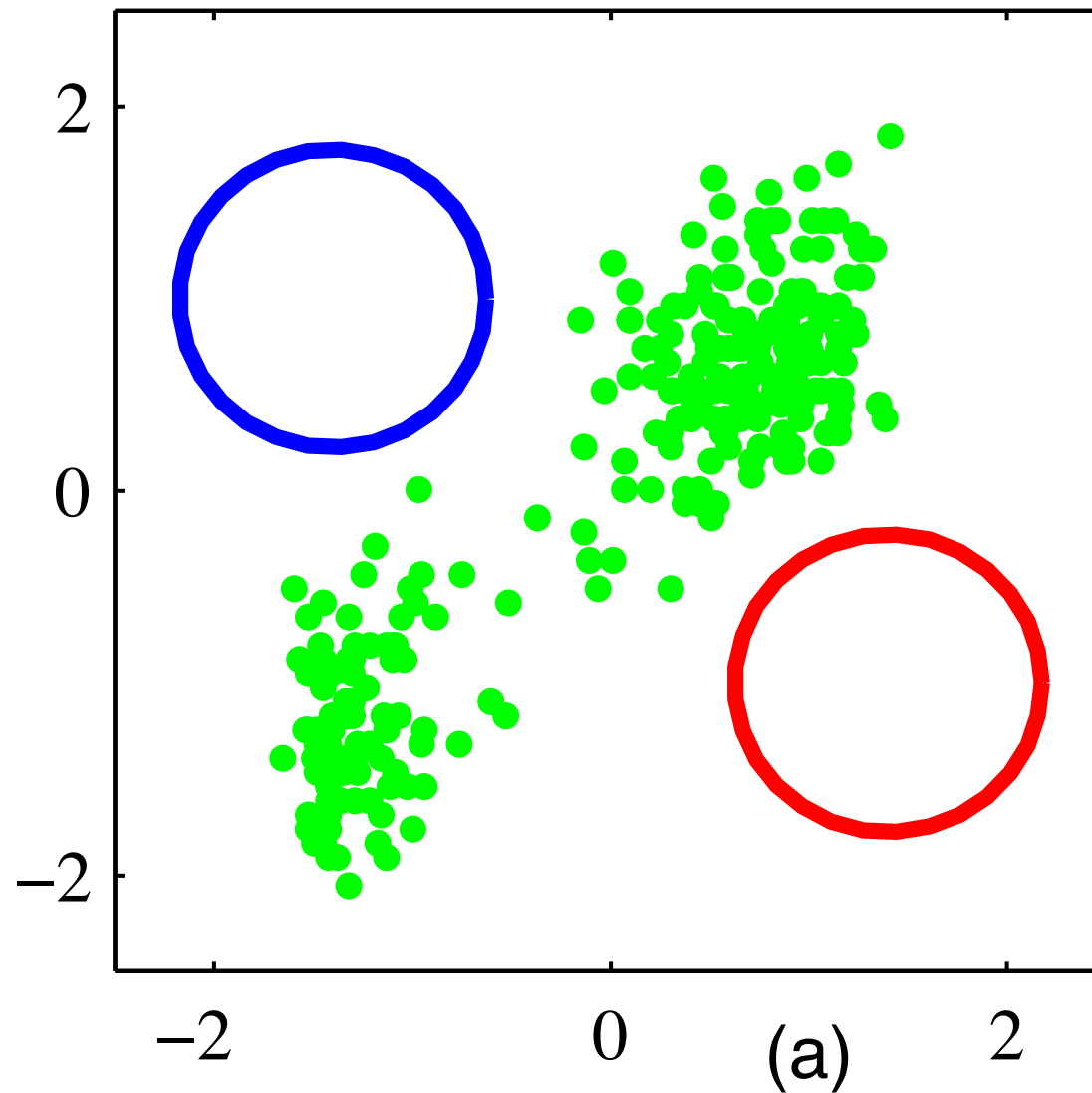


*Incomplete Data:
Points to be Clustered*

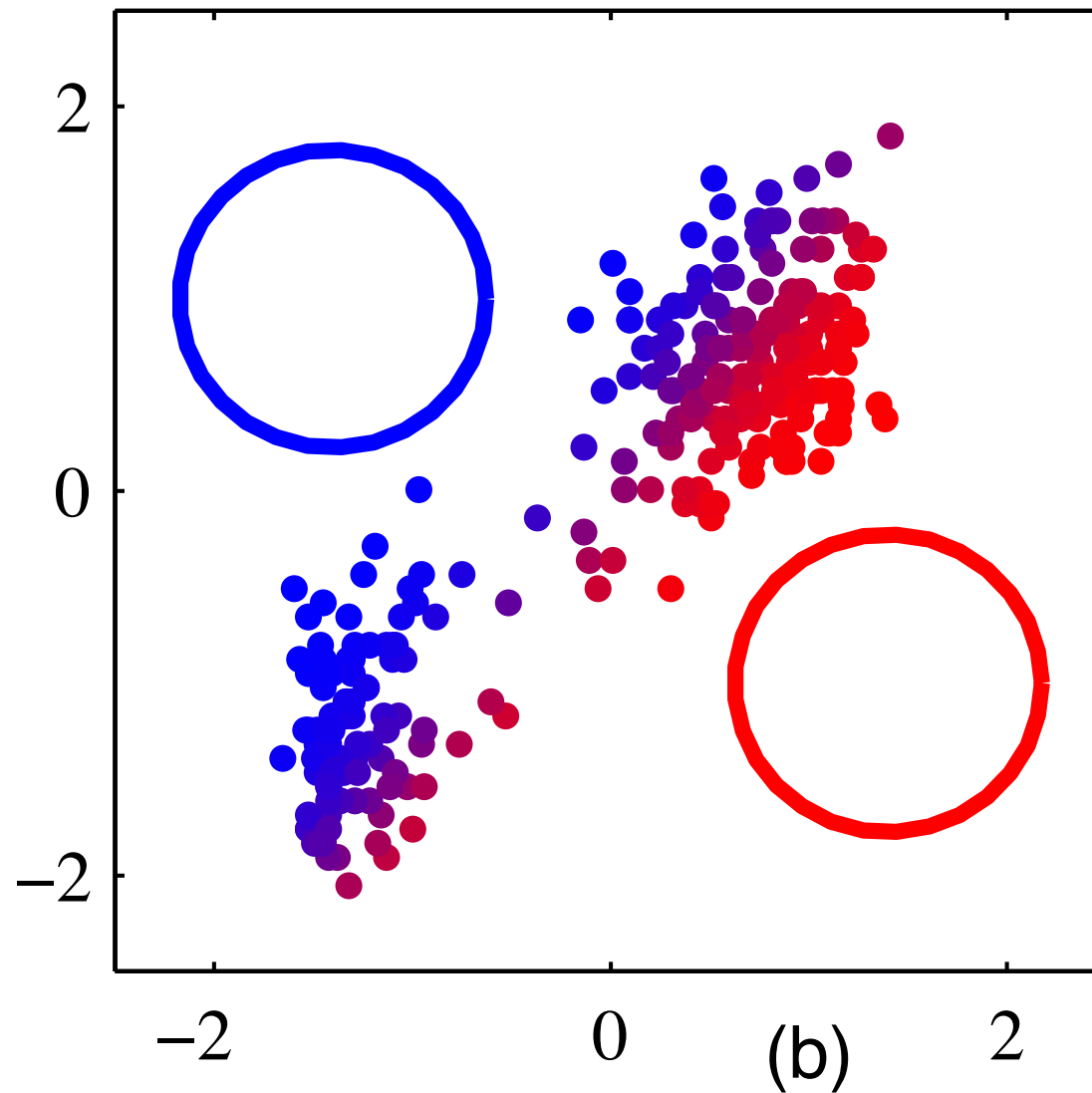
Posterior Assignment Probabilities



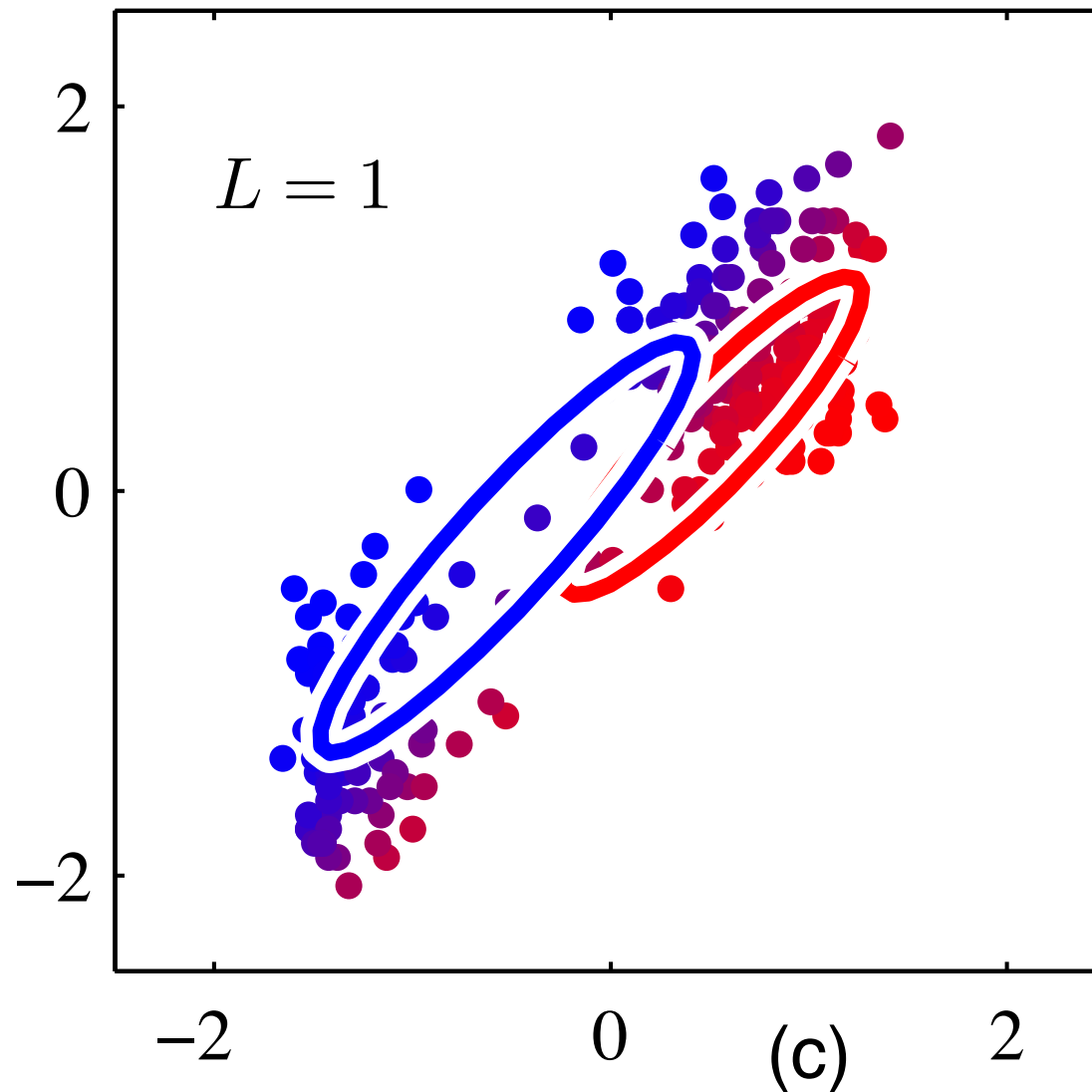
EM Algorithm



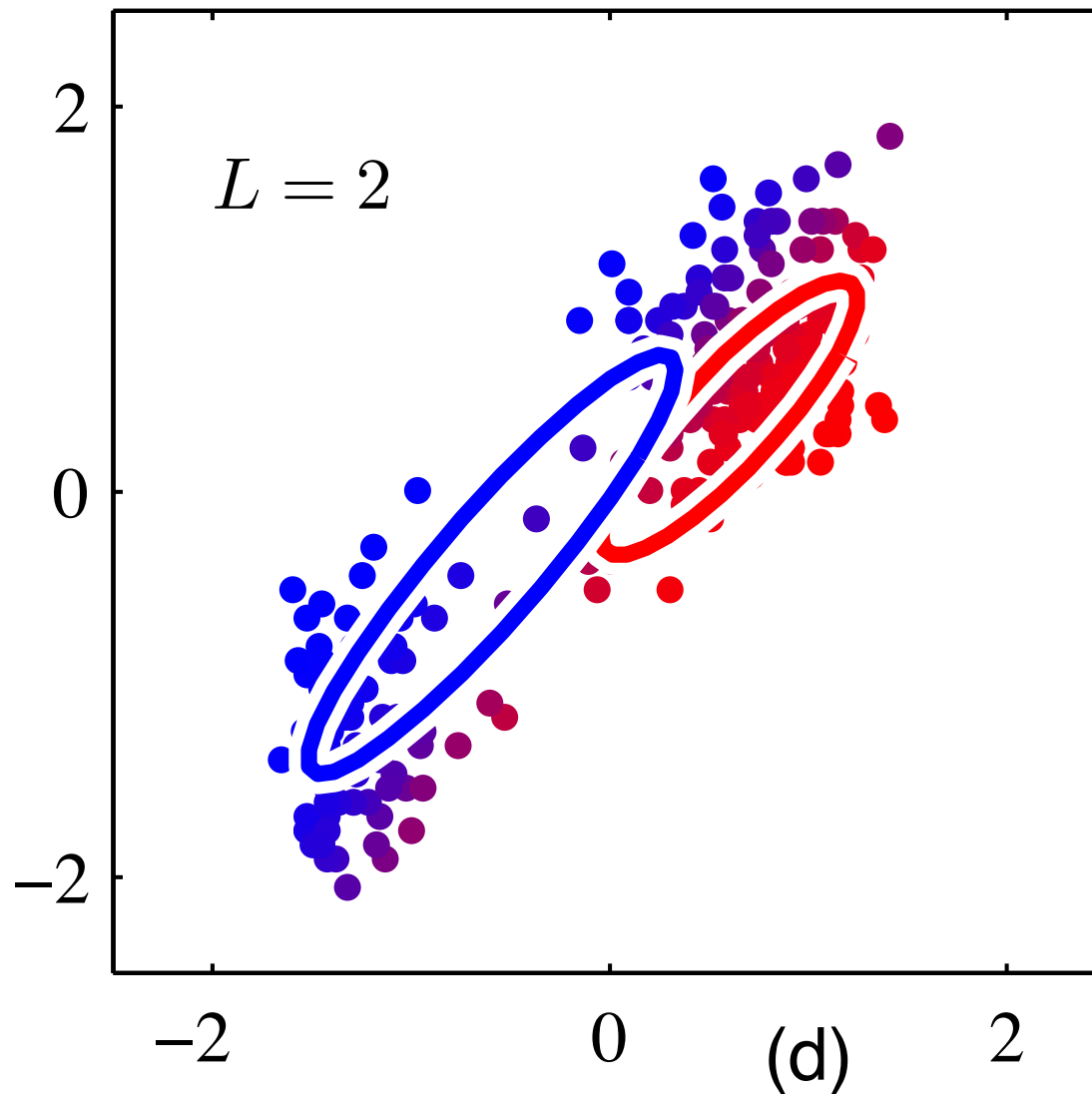
EM Algorithm



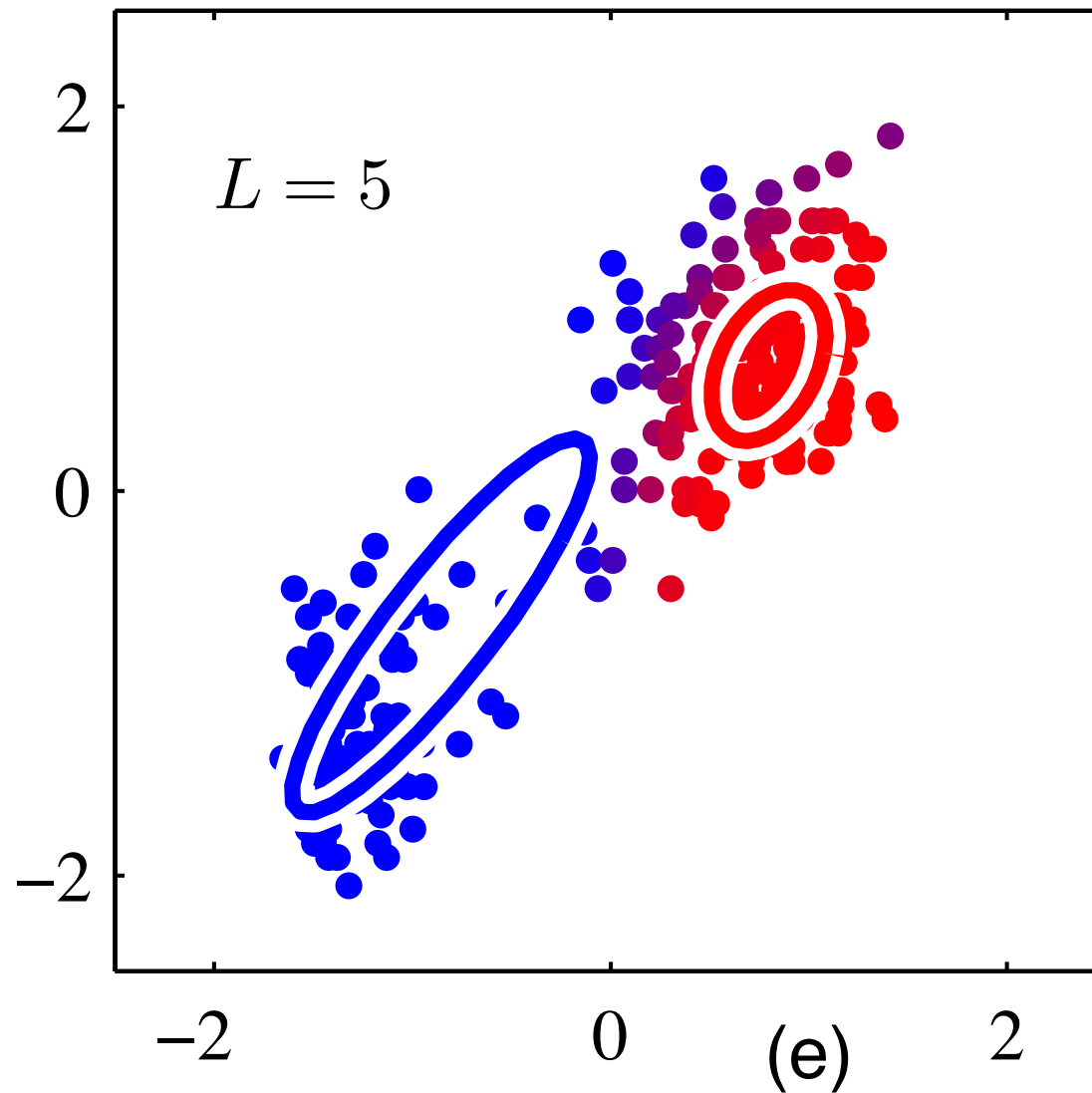
EM Algorithm



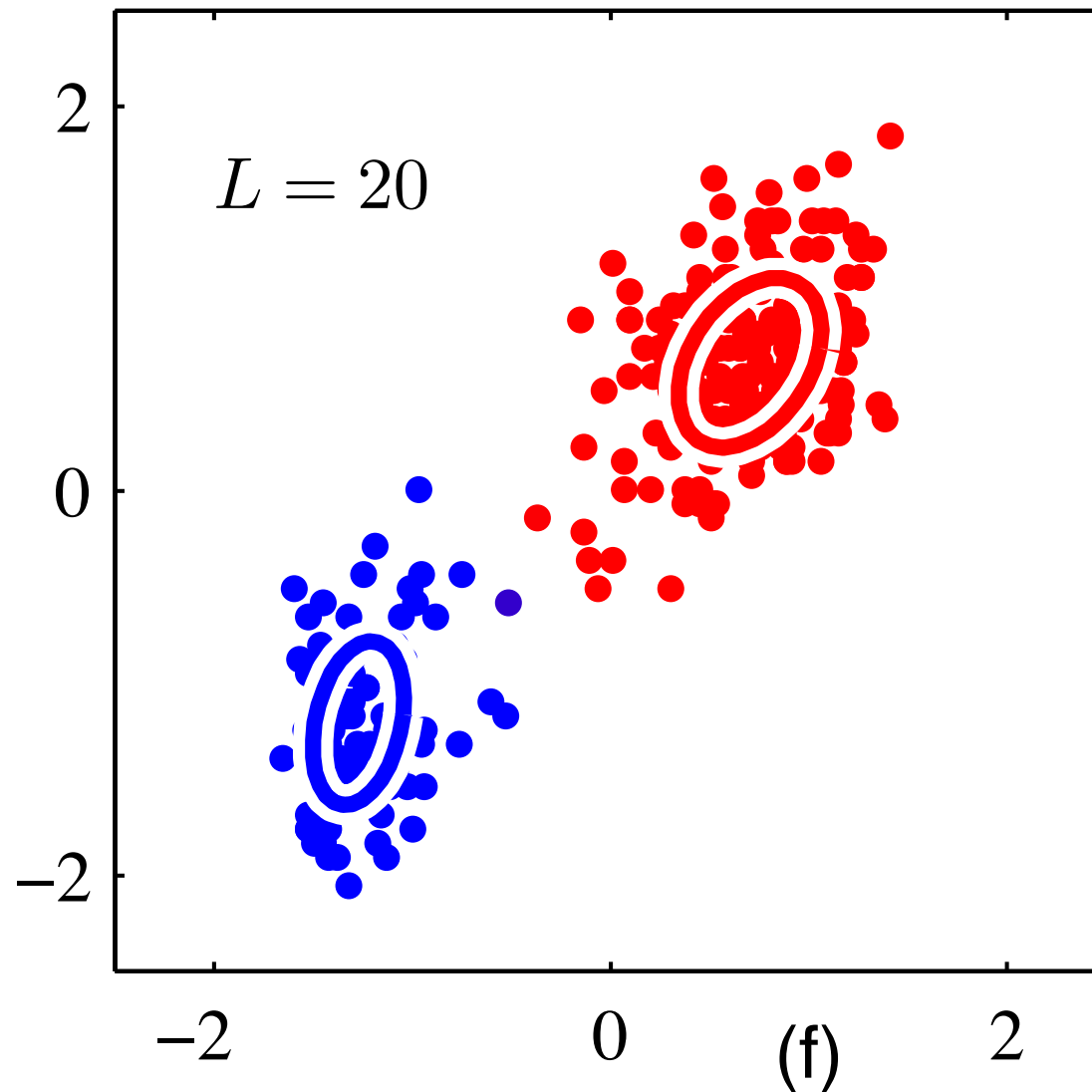
EM Algorithm



EM Algorithm



EM Algorithm



EM for Gaussian Mixtures

$$p(x_i \mid z_i, \pi, \mu, \Sigma) = \mathcal{N}(x_i \mid \mu_{z_i}, \Sigma_{z_i})$$

$$p(x_i \mid \pi, \mu, \Sigma) = \sum_{z_i=1}^K \pi_{z_i} \mathcal{N}(x_i \mid \mu_{z_i}, \Sigma_{z_i})$$

- Can easily estimate parameters if know cluster labels. How?
- What if we don't know cluster labels?