

## Quiz

Prove one of the following two statements:

1. If  $M$  is invertible then  $\text{Row } MA = \text{Row } A$  (assumes it is legal to multiply  $MA$ )
2. The union of a basis for subspace  $\mathcal{U}$  and subspace  $\mathcal{V}$  is a basis for  $\mathcal{U} \oplus \mathcal{V}$  (assumes it is legal to take the direct sum  $\mathcal{U} \oplus \mathcal{V}$ )

## Quiz

What are the rank and nullity of the following matrices?

▶ 
$$\begin{bmatrix} 0 & 1 & 2 & 3 & 4 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

▶ 
$$\begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ -2 & 0 & 1 \end{bmatrix}$$

▶ 
$$\begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ -2 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

## Using Gaussian elimination for other problems

So far:

- ▶ we know how to use Gaussian elimination to transform a matrix into echelon form;
- ▶ nonzero rows form a basis for row space of original matrix

We can do other things with Gaussian elimination:

- ▶ Solve linear systems (used in e.g. *Lights Out*)
- ▶ Find vectors in null space (used in e.g. integer factoring)

**Key idea:** keep track of transformations performed in putting matrix in echelon form.

## Gaussian elimination: recording the transformations

- ▶ Maintain  $M$  (initially identity) and  $U$  (initially  $A$ )
- ▶ Whatever transformations you do to  $U$ , do same transformations to  $M$

	0	1	2	3			$A$	$B$	$C$	$D$			$A$	$B$	$C$	$D$	
0	1	0	0	0		0	0	0	1	1		0	0	0	1	1	
1	0	1	0	0	*	1	1	0	1	1	✓ =	1	1	0	1	1	ColumnA: select row 1
2	0	0	1	0		2	1	0	0	1		2	1	0	0	1	add it to rows 2,3
3	0	0	0	1		3	1	1	1	1		3	1	1	1	1	
	0	1	2	3			$A$	$B$	$C$	$D$			$A$	$B$	$C$	$D$	
0	1	0	0	0		0	0	0	1	1	✓	0	0	0	1	1	ColumnB: select row 3
1	0	1	0	0	*	1	1	0	1	1	✓ =	1	1	0	1	1	add it to no rows
2	0	1	1	0		2	1	0	0	1		2	0	0	1	0	ColumnC: select row 0
3	0	1	0	1		3	1	1	1	1	✓	3	0	1	0	0	add it to row 2
	0	1	2	3			$A$	$B$	$C$	$D$			$A$	$B$	$C$	$D$	
0	1	0	0	0		0	0	0	1	1	✓	0	0	0	1	1	ColumnD: select row 2
1	0	1	0	0	*	1	1	0	1	1	✓ =	1	1	0	1	1	done
2	1	1	1	0		2	1	0	0	1	✓	2	0	0	0	1	

## Code for finding transformation to echelon form

- ▶ Initialize rowlist to be list of rows of  $A$
- ▶ Initialize  $M\_rowlist$  to be list of rows of identity matrix

```
for c in sorted(col_labels, key=str):
    rows_with_nonzero = [r for r in rows_left if rowlist[r][c] != 0]
    if rows_with_nonzero != []:
        pivot = rows_with_nonzero[0]
        rows_left.remove(pivot)
        new_M_rowlist.append(M_rowlist[pivot])
        for r in rows_with_nonzero[1:]:
            multiplier = rowlist[r][c]/rowlist[pivot][c]
            rowlist[r] -= multiplier*rowlist[pivot]
            M_rowlist[r] -= multiplier*M_rowlist[pivot]

    for r in rows_left: new_M_rowlist.append(M_rowlist[r])
```

Finally, return matrix  $M$  formed from new\_M\_rowlist

Code provided in module echelon

## Gaussian Elimination: Finding basis for null space

Instead of finding basis for null space of  $A$ , find basis for

$$\{\mathbf{u} : \mathbf{u} * A = \mathbf{0}\} = \text{Null } A^T$$

Input:

	A	B	C	D
0	1	0	1	0
1	1	1	1	0
2	0	1	0	1
3	1	1	1	1
4	0	0	0	1

Find  $M$  such that the matrix  $U = MA$  is in echelon form and  $M$  is invertible

0	1	0	0	0	0	*	0	1	0	1	0	=	0	1	0	1	0
1	1	1	0	0	0		1	1	1	1	0		1	0	1	0	0
2	1	1	1	0	0		2	0	1	0	1		2	0	0	0	1
3	1	0	1	1	0		3	1	1	1	1		3	0	0	0	0
4	1	1	1	0	1		4	0	0	0	1		4	0	0	0	0
<div style="display: flex; justify-content: space-around; align-items: center;"> <span style="font-size: 2em;">}</span> <span style="margin: 0 10px;"><math>M</math></span> <span style="font-size: 2em;">}</span> <span style="margin: 0 10px;"><math>A</math></span> <span style="font-size: 2em;">}</span> <span style="margin: 0 10px;"><math>U</math></span> </div>																	

Last two rows of  $U$  are zero vectors.

► Row 3 of  $U$  is (row 3 of  $M$ ) \*  $A$

## Gaussian Elimination: Finding basis for null space

Find  $M$  such that the matrix  $U = MA$  is in echelon form and  $M$  is invertible

$$\underbrace{\begin{array}{c|ccccc} & 0 & 1 & 2 & 3 & 4 \\ \hline 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 & 0 \\ 2 & 1 & 1 & 1 & 0 & 0 \\ 3 & 1 & 0 & 1 & 1 & 0 \\ 4 & 1 & 1 & 1 & 0 & 1 \end{array}}_M * \underbrace{\begin{array}{c|cccc} & A & B & C & D \\ \hline 0 & 1 & 0 & 1 & 0 \\ 1 & 1 & 1 & 1 & 0 \\ 2 & 0 & 1 & 0 & 1 \\ 3 & 1 & 1 & 1 & 1 \\ 4 & 0 & 0 & 0 & 1 \end{array}}_A = \underbrace{\begin{array}{c|cccc} & 0 & 1 & 2 & 3 \\ \hline 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 0 \\ 2 & 0 & 0 & 0 & 1 \\ 3 & 0 & 0 & 0 & 0 \\ 4 & 0 & 0 & 0 & 0 \end{array}}_U$$

Last two rows of  $U$  are zero vectors.

- ▶ Row 3 of  $U$  is (row 3 of  $M$ ) \*  $A$
- ▶ Row 4 of  $U$  is (row 4 of  $M$ ) \*  $A$

Therefore two rows in  $\{\mathbf{u} : \mathbf{u} * A = \mathbf{0}\}$  are rows 3 and 4 of  $M$ .

To show that these two rows form a basis for  $\{\mathbf{u} : \mathbf{u} * A = \mathbf{0}\}$ ....

$\dim \text{Row } A = 3$ . By Rank-Nullity Theorem,  $\dim \text{Row } A + \dim \text{Null } A^T = \text{number of rows} = 5$ .

Shows that  $\dim \text{Null } A^T = 2$ . Since  $M$  is invertible, all its rows are linearly independent.

## Gaussian Elimination: Solving system of equations

**Key idea:** keep track of transformations performed in putting matrix in echelon form.

Given matrix  $A$ , compute matrices  $M$  and  $U$  such that  $MA = U$

- ▶  $U$  is in echelon form
- ▶  $M$  is invertible

To solve  $A\mathbf{x} = \mathbf{b}$ :

- ▶ Compute  $M$  and  $U$  so that  $MA = U$
- ▶ Compute the matrix-vector product  $M\mathbf{b}$ , and solve  $U\mathbf{x} = M\mathbf{b}$ .

**Claim:** This gives correct solution to  $A\mathbf{x} = \mathbf{b}$

**Proof:** Suppose  $\mathbf{v}$  is a solution to  $U\mathbf{x} = M\mathbf{b}$ , so  $U\mathbf{v} = M\mathbf{b}$

- ▶ Multiply both sides by  $M^{-1}$ :  $M^{-1}(U\mathbf{v}) = M^{-1}(M\mathbf{b})$
- ▶ Use associativity:  $(M^{-1}U)\mathbf{v} = (M^{-1}M)\mathbf{b}$
- ▶ Cancel  $M^{-1}$  and  $M$ :  $(M^{-1}U)\mathbf{v} = \mathbb{1}\mathbf{b}$
- ▶ Use  $M^{-1}U = A$ :  $A\mathbf{v} = \mathbb{1}\mathbf{b} = \mathbf{b}$

**How** to solve  $U\mathbf{x} = M\mathbf{b}$ ?

- ▶ If  $U$  is triangular, can solve using *back-substitution* (`triangular_solve`)
- ▶ In general, can use similar algorithm