



## Matrix invertibility examples

$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}$  is not square so cannot be invertible.

$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$  is square and its columns are linearly independent so it is invertible.

$\begin{bmatrix} 1 & | & 1 & | & 2 \\ 2 & | & 1 & | & 3 \\ 3 & | & 1 & | & 4 \end{bmatrix}$  is square but columns not linearly independent so it is not invertible.

## Transpose of invertible matrix is invertible

**Theorem:** The transpose of an invertible matrix is invertible.

$$A = \left[ \begin{array}{c|ccc} \mathbf{v}_1 & \cdots & \mathbf{v}_n \end{array} \right] = \left[ \begin{array}{c} \hline \mathbf{a}_1 \\ \vdots \\ \mathbf{a}_n \\ \hline \end{array} \right] \qquad A^T = \left[ \begin{array}{c|ccc} \mathbf{a}_1 & \cdots & \mathbf{a}_n \end{array} \right]$$

**Proof:** Suppose  $A$  is invertible. Then  $A$  is square and its columns are linearly independent. Let  $n$  be the number of columns. Then  $\text{rank } A = n$ .

Because  $A$  is square, it has  $n$  rows. By Rank Theorem, rows are linearly independent.

Columns of transpose  $A^T$  are rows of  $A$ , so columns of  $A^T$  are linearly independent.

Since  $A^T$  is square and columns are linearly independent,  $A^T$  is invertible.

QED

## More matrix invertibility

Earlier we proved: *If  $A$  has an inverse  $A^{-1}$  then  $AA^{-1}$  is identity matrix*

**Converse:** If  $BA$  is identity matrix then  $A$  and  $B$  are inverses? **Not always true.**

**Theorem:** *Suppose  $A$  and  $B$  are square matrices such that  $BA$  is an identity matrix  $\mathbb{1}$ . Then  $A$  and  $B$  are inverses of each other.*

**Proof:** To show that  $A$  is invertible, need to show its columns are linearly independent.

Let  $\mathbf{u}$  be any vector such that  $A\mathbf{u} = \mathbf{0}$ . Then  $B(A\mathbf{u}) = B\mathbf{0} = \mathbf{0}$ .

On the other hand,  $(BA)\mathbf{u} = \mathbb{1}\mathbf{u} = \mathbf{u}$ , so  $\mathbf{u} = \mathbf{0}$ .

This shows  $A$  has an inverse  $A^{-1}$ . Now must show  $B = A^{-1}$ . We know  $AA^{-1} = \mathbb{1}$ .

$$BA = \mathbb{1}$$

$$(BA)A^{-1} = \mathbb{1}A^{-1} \qquad \text{by multiplying on the right by } A^{-1}$$

$$(BA)A^{-1} = A^{-1}$$

$$B(AA^{-1}) = A^{-1} \qquad \text{by associativity of matrix-matrix mult}$$

$$B\mathbb{1} = A^{-1}$$

$$B = A^{-1}$$

*QED*

## Representations of vector spaces

Two important ways to represent a vector space:

As the solution set of homogeneous linear system

$$\mathbf{a}_1 \cdot \mathbf{x} = 0, \dots, \mathbf{a}_m \cdot \mathbf{x} = 0$$

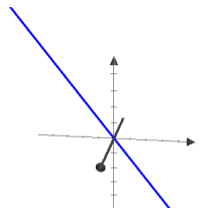
Equivalently, Null  $\left[ \begin{array}{c} \mathbf{a}_1 \\ \hline \vdots \\ \mathbf{a}_m \end{array} \right]$

As Span  $\{\mathbf{b}_1, \dots, \mathbf{b}_k\}$

Equivalently,

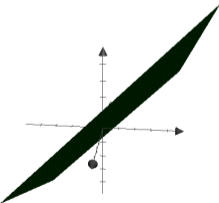
Col  $\left[ \begin{array}{c|c|c} \mathbf{b}_1 & \cdots & \mathbf{b}_k \end{array} \right]$

## Conversions between the two representations



$$\{[x, y, z] : \\ [4, -1, 1] \cdot [x, y, z] = 0, \\ [0, 1, 1] \cdot [x, y, z] = 0\}$$

$$\text{Span} \{[1, 2, -2]\}$$



$$\text{Span} \{[4, -1, 1], [0, 1, 1]\}$$

$$\{[x, y, z] : [1, 2, -2] \cdot [x, y, z] = 0\}$$

## Conversions for affine spaces?

- ▶ From representation as solution set of linear system to representation as affine hull
- ▶ From representation as affine hull to representation as solution set of linear system

## Conversions for affine spaces?

From representation as solution set of linear system to representation as affine hull

- ▶ *input*: linear system  $A\mathbf{x} = \mathbf{b}$
- ▶ *output*: vectors whose affine hull is the solution set of the linear system.

- 1 Let  $\mathbf{u}$  be one solution to the linear system.
- 2 Consider the corresponding homogeneous system  $A\mathbf{x} = \mathbf{0}$ .  
Its solution set, the null space of  $A$ , is a vector space  $\mathcal{V}$ .
- 3 Let  $\mathbf{b}_1, \dots, \mathbf{b}_k$  be generators for  $\mathcal{V}$ .
- 4 Then the solution set of the original linear system is the affine hull of  $\mathbf{u}, \mathbf{b}_1 + \mathbf{u}, \mathbf{b}_2 + \mathbf{u}, \dots, \mathbf{b}_k + \mathbf{u}$ .

$$\begin{bmatrix} 1 & 2 & 1 \\ -1 & 2 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\mathbf{u} = [-0.5, 0.75, 0]$$

$$\begin{bmatrix} 1 & 2 & 1 \\ -1 & 2 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\mathbf{b}_1 = [2, -3, 4]$$

$$[-0.5, -0.75, 0] \text{ and } [-0.5, -0.75, 0] + [2, -3, 4]$$

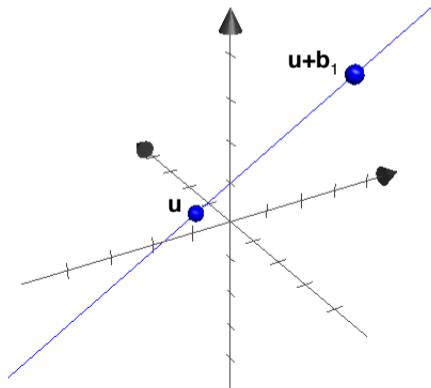
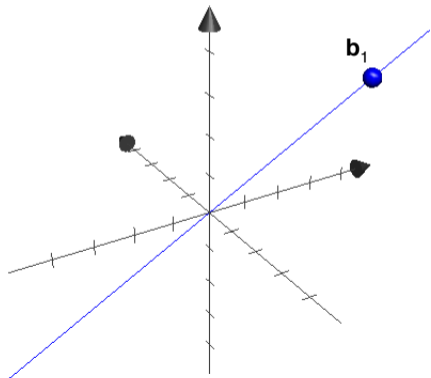


## From representation as solution set to representation as affine hull

One solution to equation  $\begin{bmatrix} 1 & 2 & 1 \\ -1 & 2 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$  is  $\mathbf{u} = [-0.5, 0.75, 0]$

Null space of  $\begin{bmatrix} 1 & 2 & 1 \\ -1 & 2 & 2 \end{bmatrix}$  is  $\text{Span}\{\mathbf{b}_1\}$ :

Solution set of equation is  $\mathbf{u} + \text{Span}\{\mathbf{b}_1\}$ ,  
i.e. the affine hull of  $\mathbf{u}$  and  $\mathbf{u} + \mathbf{b}_1$



## Representations of vector spaces

Two important ways to represent a vector space:

As the solution set of homogeneous linear system

$$\mathbf{a}_1 \cdot \mathbf{x} = 0, \dots, \mathbf{a}_m \cdot \mathbf{x} = 0$$

Equivalently, Null  $\left[ \begin{array}{c} \mathbf{a}_1 \\ \hline \vdots \\ \hline \mathbf{a}_m \end{array} \right]$

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How to transform between these two representations?

### Problem 1 (From left to right):

- ▶ *input*: homogeneous linear system  $\mathbf{a}_1 \cdot \mathbf{x} = 0, \dots, \mathbf{a}_m \cdot \mathbf{x} = 0$ ,
- ▶ *output*: basis  $\mathbf{b}_1, \dots, \mathbf{b}_k$  for solution set

### Problem 2 (From right to left):

- ▶ *input*: independent vectors  $\mathbf{b}_1, \dots, \mathbf{b}_k$ ,
- ▶ *output*: homogeneous linear system  $\mathbf{a}_1 \cdot \mathbf{x} = 0, \dots, \mathbf{a}_m \cdot \mathbf{x} = 0$  whose solution set equals

## Reformulating Problem 1

- ▶ *input*: homogeneous linear system  $\mathbf{a}_1 \cdot \mathbf{x} = 0, \dots, \mathbf{a}_m \cdot \mathbf{x} = 0$ ,
- ▶ *output*: basis  $\mathbf{b}_1, \dots, \mathbf{b}_k$  for solution set

Let's express this in the language of matrices:

- ▶ *input*: matrix  $A = \begin{bmatrix} \mathbf{a}_1 \\ \hline \vdots \\ \hline \mathbf{a}_m \end{bmatrix}$
- ▶ *output*: matrix  $B = \left[ \begin{array}{c|c|c} \mathbf{b}_1 & \cdots & \mathbf{b}_k \end{array} \right]$  such that  $\text{Col } B = \text{Null } A$

Can require the **rows** of the **input matrix**  $A$  to be linearly independent. (Discarding a superfluous row does not change the null space of  $A$ .)

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## Reformulating the reformulation of Problem 1

- ▶ *input*: matrix  $A$  with independent rows
- ▶ *output*: matrix  $B$  with independent columns such that  $\text{Col } B = \text{Null } A$

By Rank-Nullity Theorem,  $\text{rank } A + \text{nullity } A = n$

Because rows of  $A$  are linearly independent,  $\text{rank } A = m$ ,

so  $m + \text{nullity } A = n$

Requiring  $\text{Col } B = \text{Null } A$  is the same as requiring

(i)  $\text{Col } B$  is a subspace of  $\text{Null } A$

(ii)  $\dim \text{Col } B = \text{nullity } A$

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(i)  $\text{Col } B$  is a subspace of  $\text{Null } A \implies$  same as requiring  $AB = \begin{bmatrix} 0 & \cdots & 0 \\ \vdots & & \vdots \\ 0 & \cdots & 0 \end{bmatrix}$

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- (ii)  $\dim \text{Col } B = \text{nullity } A \implies$  same as requiring number of columns of  $B = \text{nullity } A$   
same as requiring number of columns of  $B = n - m$

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same as requiring number of columns of  $B = n - m$

- ▶ *input*:  $m \times n$  matrix  $A$  with independent rows
- ▶ *output*: matrix  $B$  with  $n - m$  independent columns such that  $AB = \begin{bmatrix} \mathbf{0} \end{bmatrix}$

# Hypothesize a procedure for reformulation of Problem 1

## Problem 1:

- ▶ *input*:  $m \times n$  matrix  $A$  with independent rows
- ▶ *output*: matrix  $B$  with  $n - m$  independent columns such that  $AB = \begin{bmatrix} \mathbf{0} \end{bmatrix}$

Define procedure `null_space_basis(M)` with this spec:

- ▶ *input*:  $r \times n$  matrix  $M$  with independent rows
- ▶ *output*: matrix  $C$  with  $n - r$  independent columns such that  $MC = \begin{bmatrix} \mathbf{0} \end{bmatrix}$

## Reformulating Problem 2

- ▶ *input*: independent vectors  $\mathbf{b}_1, \dots, \mathbf{b}_k$ ,
- ▶ *output*: homogeneous linear system  $\mathbf{a}_1 \cdot \mathbf{x} = 0, \dots, \mathbf{a}_m \cdot \mathbf{x} = 0$  whose solution set equals  $\text{Span} \{ \mathbf{b}_1, \dots, \mathbf{b}_k \}$

Let's express this in the language of matrices:

- ▶ *input*:  $n \times k$  matrix  $B$  with independent columns
- ▶ *output*: matrix  $A$  with independent rows such that  $\text{Null } A = \text{Col } B$

As before, Rank-Nullity Theorem implies

$$\text{number of rows of } A + \text{nullity } A = \text{number of columns of } A$$

As before, requiring  $\text{Null } A = \text{Col } B$  is the same as requiring

- $AB = \begin{bmatrix} \mathbf{0} \end{bmatrix}$
- number of rows of  $A = n - k$

- ▶ *input*:  $n \times k$  matrix  $B$  with independent rows
- ▶ *output*: matrix  $A$  with  $n - k$  independent rows such that  $AB = \begin{bmatrix} \mathbf{0} \end{bmatrix}$

## Solving Problem 2 with the procedure for Problem 1

### Problem 1:

- ▶ *input*:  $m \times n$  matrix  $A$  with independent rows
- ▶ *output*: matrix  $B$  with  $n - m$  independent columns such that  $AB = \begin{bmatrix} \mathbf{0} \end{bmatrix}$

Define procedure `null_space_basis(M)`

- ▶ *input*:  $r \times n$  matrix  $M$  with independent rows
- ▶ *output*: matrix  $C$  with  $n - r$  independent columns such that  $MC = \begin{bmatrix} \mathbf{0} \end{bmatrix}$

### Problem 2:

- ▶ *input*:  $n \times k$  matrix  $B$  with independent rows
- ▶ *output*: matrix  $A$  with  $n - k$  independent rows such that  $AB = \begin{bmatrix} \mathbf{0} \end{bmatrix}$

To solve Problem 2, call `null_space_basis( $B^T$ )`.

Returns matrix  $A^T$  with independent columns such that  $B^T A^T = \begin{bmatrix} \mathbf{0} \end{bmatrix}$

Since  $B^T$  is  $k \times n$  matrix,  $A^T$  has  $n - k$  columns.

Therefore  $AB = \begin{bmatrix} \mathbf{0} \end{bmatrix}$  and  $A$  has  $n - k$  independent rows. Therefore  $A$  is solution to Problem