

Dynamic Programming



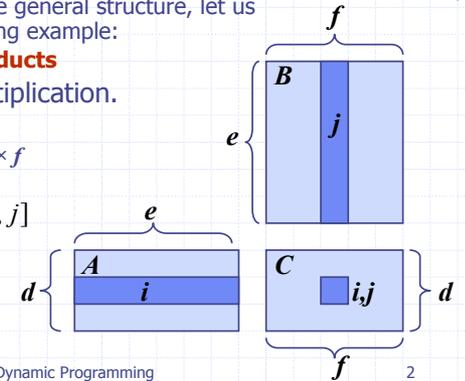
Matrix Chain-Products (not in book)



- ◆ **Dynamic Programming** is a general algorithm design paradigm.
 - Rather than give the general structure, let us first give a motivating example:
 - **Matrix Chain-Products**
- ◆ **Review: Matrix Multiplication.**
 - $C = A * B$
 - A is $d \times e$ and B is $e \times f$

$$C[i, j] = \sum_{k=0}^{e-1} A[i, k] * B[k, j]$$

- $O(ef)$ time



Matrix Chain-Products



◆ Matrix Chain-Product:

- Compute $A = A_0 * A_1 * \dots * A_{n-1}$
- A_i is $d_i \times d_{i+1}$
- Problem: How to parenthesize?

◆ Example

- B is 3×100
- C is 100×5
- D is 5×5
- $(B * C) * D$ takes $1500 + 75 = 1575$ ops
- $B * (C * D)$ takes $1500 + 2500 = 4000$ ops

An Enumeration Approach



◆ Matrix Chain-Product Alg.:

- Try all possible ways to parenthesize $A = A_0 * A_1 * \dots * A_{n-1}$
- Calculate number of ops for each one
- Pick the one that is best

◆ Running time:

- The number of paranthesizations is equal to the number of binary trees with n nodes
- This is **exponential!**
- It is called the Catalan number, and it is almost 4^n .
- This is a terrible algorithm!

A Greedy Approach



- ◆ Idea #1: repeatedly select the product that uses (up) the most operations.
- ◆ Counter-example:
 - A is 10×5
 - B is 5×10
 - C is 10×5
 - D is 5×10
 - Greedy idea #1 gives $(A*B)*(C*D)$, which takes $500+1000+500 = 2000$ ops
 - $A*((B*C)*D)$ takes $500+250+250 = 1000$ ops

Another Greedy Approach



- ◆ Idea #2: repeatedly select the product that uses the fewest operations.
- ◆ Counter-example:
 - A is 101×11
 - B is 11×9
 - C is 9×100
 - D is 100×99
 - Greedy idea #2 gives $A*((B*C)*D)$, which takes $109989+9900+108900=228789$ ops
 - $(A*B)*(C*D)$ takes $9999+89991+89100=189090$ ops
- ◆ The greedy approach is not giving us the optimal value.

A "Recursive" Approach



- ◆ Define **subproblems**:
 - Find the best parenthesization of $A_i * A_{i+1} * \dots * A_j$.
 - Let $N_{i,j}$ denote the number of operations done by this subproblem.
 - The optimal solution for the whole problem is $N_{0,n-1}$.
- ◆ **Subproblem optimality**: The optimal solution can be defined in terms of optimal subproblems
 - There has to be a final multiplication (root of the expression tree) for the optimal solution.
 - Say, the final multiply is at index i : $(A_0 * \dots * A_i) * (A_{i+1} * \dots * A_{n-1})$.
 - Then the optimal solution $N_{0,n-1}$ is the sum of two optimal subproblems, $N_{0,i}$ and $N_{i+1,n-1}$ plus the time for the last multiply.
 - If the global optimum did not have these optimal subproblems, we could define an even better "optimal" solution.

A Characterizing Equation



- ◆ The global optimal has to be defined in terms of optimal subproblems, depending on where the final multiply is at.
- ◆ Let us consider all possible places for that final multiply:
 - Recall that A_i is a $d_i \times d_{i+1}$ dimensional matrix.
 - So, a characterizing equation for $N_{i,j}$ is the following:

$$N_{i,j} = \min_{i \leq k < j} \{ N_{i,k} + N_{k+1,j} + d_i d_{k+1} d_{j+1} \}$$

- ◆ Note that subproblems are not independent - the **subproblems overlap**.

A Dynamic Programming Algorithm



- ◆ Since **subproblems overlap**, we don't use recursion.
- ◆ Instead, we construct optimal subproblems "bottom-up."
- ◆ $N_{i,j}$'s are easy, so start with them
- ◆ Then do length 2,3,... subproblems, and so on.
- ◆ Running time: $O(n^3)$

Algorithm *matrixChain(S)*:

Input: sequence S of n matrices to be multiplied

Output: number of operations in an optimal parenthization of S

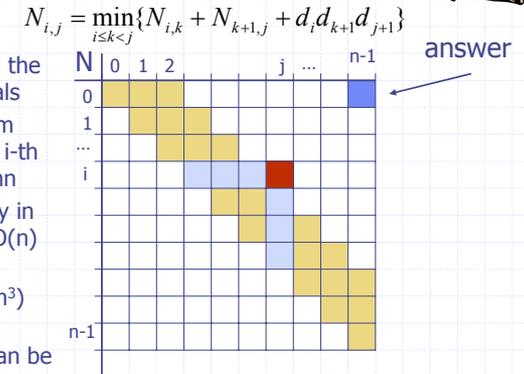
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for  $i \leftarrow 1$  to  $n-1$  do
   $N_{i,i} \leftarrow 0$ 
  for  $b \leftarrow 1$  to  $n-1$  do
    for  $i \leftarrow 0$  to  $n-b-1$  do
       $j \leftarrow i+b$ 
       $N_{i,j} \leftarrow +\text{infinity}$ 
      for  $k \leftarrow i$  to  $j-1$  do
         $N_{i,j} \leftarrow \min\{N_{i,j}, N_{i,k} + N_{k+1,j} + d_i d_{k+1} d_{j+1}\}$ 
  
```

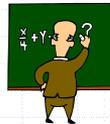
A Dynamic Programming Algorithm Visualization



- ◆ The bottom-up construction fills in the N array by diagonals
- ◆ $N_{i,j}$ gets values from previous entries in i -th row and j -th column
- ◆ Filling in each entry in the N table takes $O(n)$ time.
- ◆ Total run time: $O(n^3)$
- ◆ Getting actual parenthization can be done by remembering "k" for each N entry



The General Dynamic Programming Technique



- ◆ Applies to a problem that at first seems to require a lot of time (possibly exponential), provided we have:
 - **Simple subproblems:** the subproblems can be defined in terms of a few variables, such as j, k, l, m , and so on.
 - **Subproblem optimality:** the global optimum value can be defined in terms of optimal subproblems
 - **Subproblem overlap:** the subproblems are not independent, but instead they overlap (hence, should be constructed bottom up).

Subsequences (§ 11.5.1)

- ◆ A **subsequence** of a character string $x_0x_1x_2\dots x_{n-1}$ is a string of the form $x_{i_1}x_{i_2}\dots x_{i_k}$, where $i_j < i_{j+1}$.
- ◆ Not the same as substring!
- ◆ Example String: ABCDEFGHIJK
 - Subsequence: ACEGJIK
 - Subsequence: DFGHK
 - Not subsequence: DAGH

The Longest Common Subsequence (LCS) Problem

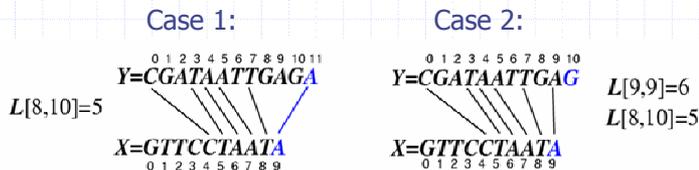
- ◆ Given two strings X and Y , the longest common subsequence (LCS) problem is to find a longest subsequence common to both X and Y
- ◆ Has applications to DNA similarity testing (alphabet is $\{A,C,G,T\}$)
- ◆ Example: ABCDEFG and XZACKDFWGH have ACDFG as a longest common subsequence

A Poor Approach to the LCS Problem

- ◆ A Brute-force solution:
 - Enumerate all subsequences of X
 - Test which ones are also subsequences of Y
 - Pick the longest one.
- ◆ Analysis:
 - If X is of length n , then it has 2^n subsequences
 - This is an exponential-time algorithm!

A Dynamic-Programming Approach to the LCS Problem

- ◆ Define $L[i,j]$ to be the length of the longest common subsequence of $X[0..i]$ and $Y[0..j]$.
- ◆ Allow for -1 as an index, so $L[-1,k] = 0$ and $L[k,-1]=0$, to indicate that the null part of X or Y has no match with the other.
- ◆ Then we can define $L[i,j]$ in the general case as follows:
 1. If $x_i=y_j$, then $L[i,j] = L[i-1,j-1] + 1$ (we can add this match)
 2. If $x_i \neq y_j$, then $L[i,j] = \max\{L[i-1,j], L[i,j-1]\}$ (we have no match here)



An LCS Algorithm

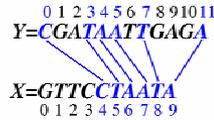
Algorithm $LCS(X,Y)$:
Input: Strings X and Y with n and m elements, respectively
Output: For $i = 0, \dots, n-1$, $j = 0, \dots, m-1$, the length $L[i,j]$ of a longest string that is a subsequence of both the string $X[0..i] = x_0x_1x_2\dots x_i$ and the string $Y[0..j] = y_0y_1y_2\dots y_j$

```

for i=1 to n-1 do
  L[i,-1] = 0
for j=0 to m-1 do
  L[-1,j] = 0
for i=0 to n-1 do
  for j=0 to m-1 do
    if  $x_i = y_j$  then
      L[i,j] = L[i-1,j-1] + 1
    else
      L[i,j] = max{L[i-1,j], L[i,j-1]}
return array L
    
```

Visualizing the LCS Algorithm

| L | -1 | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 |
|----|----|---|---|---|---|---|---|---|---|---|---|----|----|
| -1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| 1 | 0 | 0 | 1 | 1 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 | 2 |
| 2 | 0 | 0 | 1 | 1 | 2 | 2 | 2 | 3 | 3 | 3 | 3 | 3 | 3 |
| 3 | 0 | 1 | 1 | 1 | 2 | 2 | 2 | 3 | 3 | 3 | 3 | 3 | 3 |
| 4 | 0 | 1 | 1 | 1 | 2 | 2 | 2 | 3 | 3 | 3 | 3 | 3 | 3 |
| 5 | 0 | 1 | 1 | 1 | 2 | 2 | 2 | 3 | 4 | 4 | 4 | 4 | 4 |
| 6 | 0 | 1 | 1 | 2 | 2 | 3 | 3 | 3 | 4 | 4 | 5 | 5 | 5 |
| 7 | 0 | 1 | 1 | 2 | 2 | 3 | 4 | 4 | 4 | 4 | 5 | 5 | 6 |
| 8 | 0 | 1 | 1 | 2 | 3 | 3 | 4 | 5 | 5 | 5 | 5 | 5 | 6 |
| 9 | 0 | 1 | 1 | 2 | 3 | 4 | 4 | 5 | 5 | 5 | 6 | 6 | 6 |



Analysis of LCS Algorithm

- ◆ We have two nested loops
 - The outer one iterates n times
 - The inner one iterates m times
 - A constant amount of work is done inside each iteration of the inner loop
 - Thus, the total running time is $O(nm)$
- ◆ Answer is contained in $L[n,m]$ (and the subsequence can be recovered from the L table).